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# **A Novel Methodology for the Design of Isophoric Phased Arrays**

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# 1 Irregular Phased Array Square ( $2 \times 2, 4 \times 4$ )-Tiling

## 1.1 Antenna Aperture: Rectangle $40 \times 40$ Elements

### 1.1.1 ISOPHORIC EXCITATIONS

**Multi-Objective Optimization-based Tiling Method:** ( $m \times m, 2m \times 2m$ )-BMTM NSGA-III

**Array Analysis Parameters:**

- Total Number of Elements:  $J = 1600$ .
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 512;
- Number of Samples along  $v$ : 512;
- Tapering: Isophoric;

- Steering Direction:

Scan n.	$\theta_s$	$\phi_s$
1	$0^\circ$	$0^\circ$
2	$5^\circ$	$0^\circ$
3	$5^\circ$	$45^\circ$
4	$5^\circ$	$90^\circ$
5	$5^\circ$	$135^\circ$
6	$5^\circ$	$180^\circ$
7	$5^\circ$	$225^\circ$
8	$5^\circ$	$270^\circ$
9	$5^\circ$	$315^\circ$

**Tiling Parameters:**

- *Small Tile:*  $S_1$ -tile:  $1 \times 1$ ;
- *Big Tile:*  $S_2$ -tile:  $2 \times 2$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 4;
- Clustering Ratio  $S_2$ -tile: 1 : 16;
- Total Number of Configurations:  $\Gamma = 2.70 \times 10^{48}$ ;

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### NSGA-III Parameters:

- Population size:  $P = 100$ ;
- Chromosome length:  $l = 19$ ;
- Maximum number of generations:  $K = 2000$ ;
- Maximum number of functional evaluation calls:  $NFE = P \times K = 2.0 \times 10^5$ ;
- Objectives:
  1. Side-lobe Level:  $SLL$  [dB];
  2. Number of TRM:  $TRM$ ;
- Number of initial Populations:  $N_{pop} = 1$ ;
- Number of GA random Seeds:  $N_{Seed} = 1$ ;
- Total number of Runs:  $N_{Runs} = N_{pop} \times N_{Seed} = 1$ ;

## NUMERICAL RESULTS

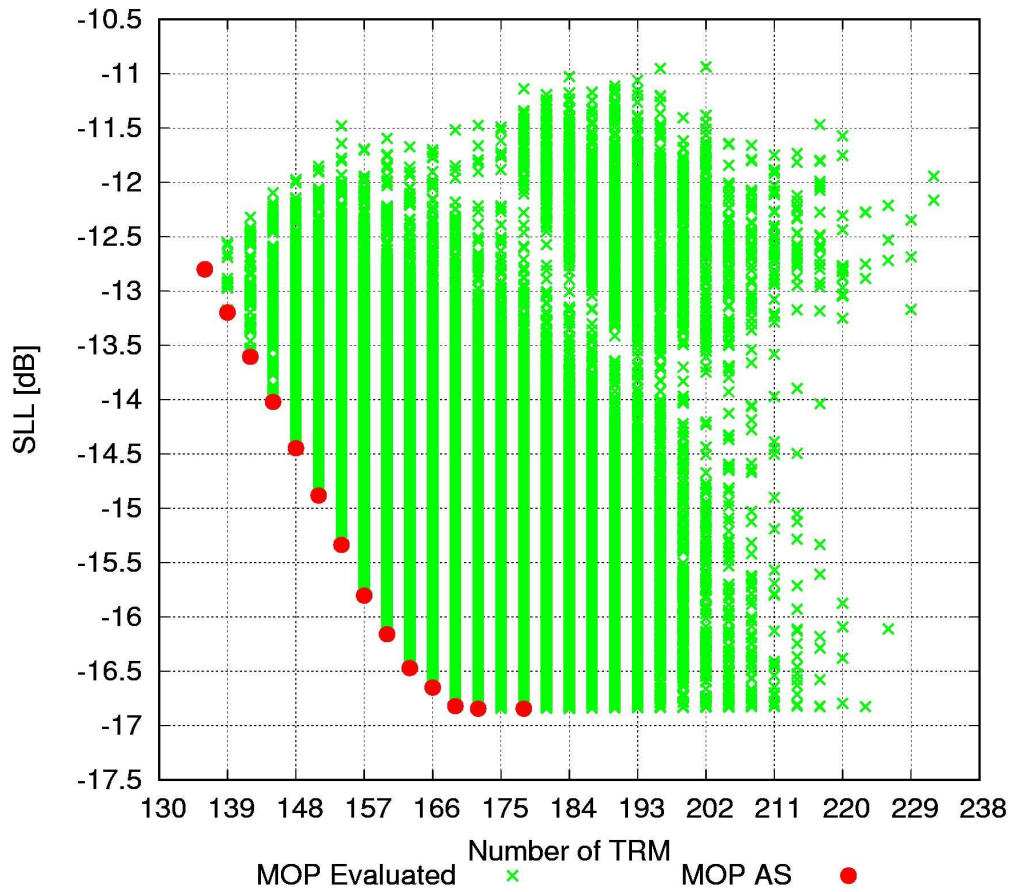


Figure 1: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 40$ ,  $q = 40$ ,  $J = 1600$ ) - Approximation Set: Objective 1 (SLL) vs. Objective 2 (Number of TRM).

### Statistics

	Max	Min	Mean	Variance
SLL [dB]	-10.93	-16.84	-14.56	1.62

Table I: Runs Statistics

Number of TRM=178

Direction ( $\theta = 0^\circ, \phi = 0^\circ$ )

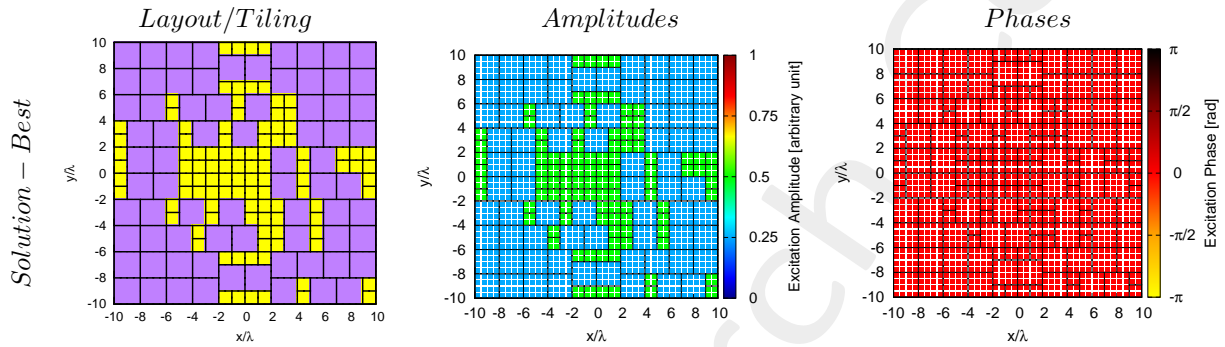


Figure 2: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Tiling configuration and weights coefficients value.

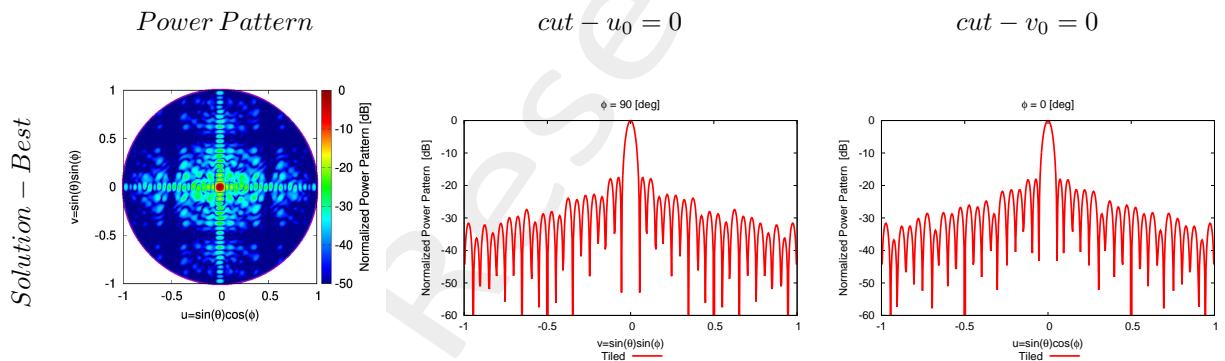


Figure 3: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]
<i>Solution – Best</i>	-17.55	36.40	2.66	2.66

Table II: Pattern descriptors for the presented solutions.

Direction ( $\theta = 5^\circ, \phi = 0^\circ$ )

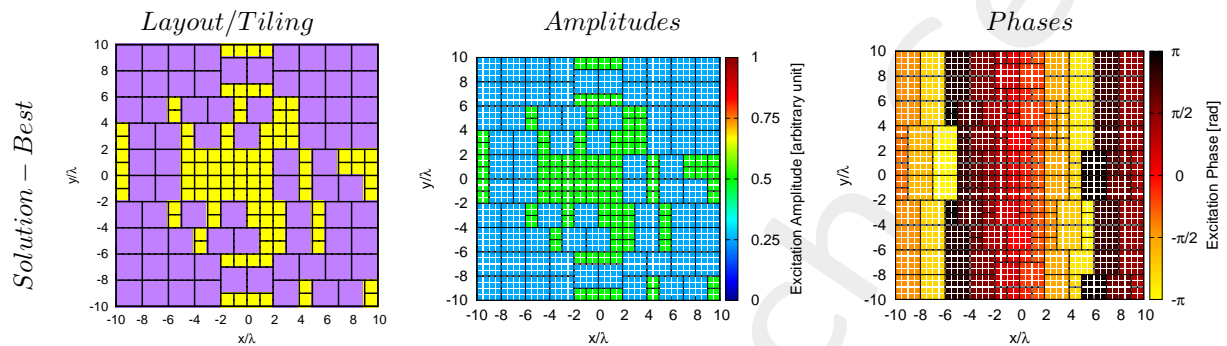


Figure 4: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Tiling configuration and weights coefficients value.

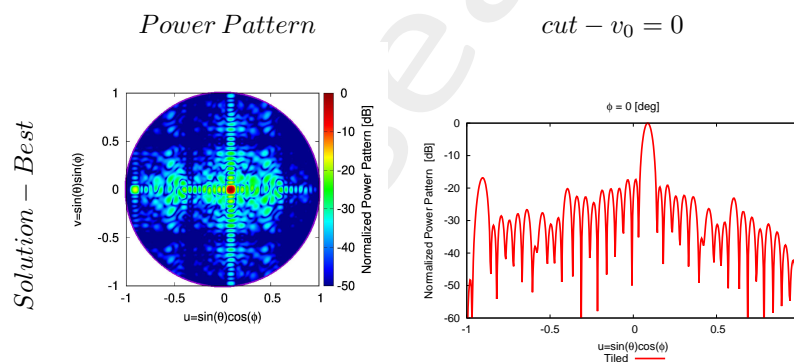


Figure 5: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]
<i>Solution – Best</i>	-16.85	36.00	2.68	2.67

Table III: Pattern descriptors for the presented solutions.

Direction ( $\theta = 5^\circ, \phi = 90^\circ$ )

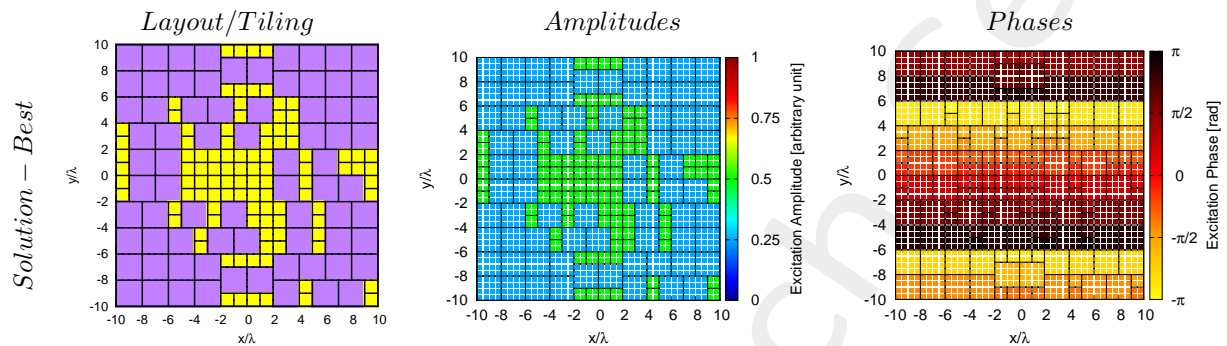


Figure 6: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Tiling configuration and weights coefficients value.

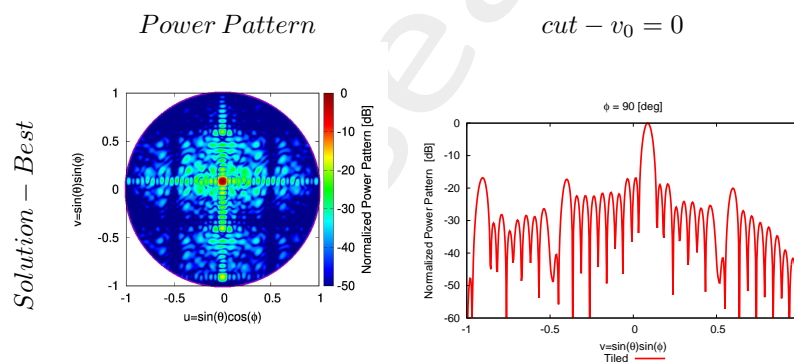


Figure 7: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 40, q = 40, J = 1600$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]
<i>Solution – Best</i>	-16.84	36.00	2.68	2.67

Table IV: Pattern descriptors for the presented solutions.



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## 2 Irregular Phased Array Square ( $4 \times 4, 16 \times 16$ )-Tiling

### 2.1 Antenna Aperture: Rectangle $120 \times 120$ Elements

#### 2.1.1 ISOPHORIC EXCITATIONS

**Optimization-based Tiling Method:** ( $m \times m, sm \times sm$ )-BMTM Integer GA

**Array Analysis Parameters:**

- Total Number of Elements:  $J = 14400$ ;
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 512;
- Number of Samples along  $v$ : 512;
- Steering Direction:  $(\theta_s, \phi_s) = \{(0^\circ, 0^\circ)\}$ ;
- Tapering: Isophoric;

**Tiling Parameters:**

- *Small* Tile:  $S_1$ -tile:  $4 \times 4$ ;
- *Big* Tile:  $S_2$ -tile:  $16 \times 16$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 16;
- Clustering Ratio  $S_2$ -tile: 1 : 256;

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### GA Parameters:

- GA type: *Integer Genetic Algorithm*.
- Population size:  $P = 50$ ;
- Crossover probability:  $p_{CR} = 0.9$ ;
- Mutation probability:  $p_M = 0.1$ ;
- Chromosome length:  $l = 27$ ;
- Maximum number of generations:  $K = 10000$ ;
- Maximum number of allowed TRM:  $TRM = 900$ ;
- Maximum number of functional evaluation calls:  $NFE = P \times K = 5.0 \times 10^5$ ;
- Number of initial Populations:  $N_{pop} = 1$ ;
- Number of GA random Seeds:  $N_{Seed} = 3$ ;
- Total number of Runs:  $N_{Runs} = N_{pop} \times N_{Seed} = 3$ ;

## NUMERICAL RESULTS

Number of TRM: 465

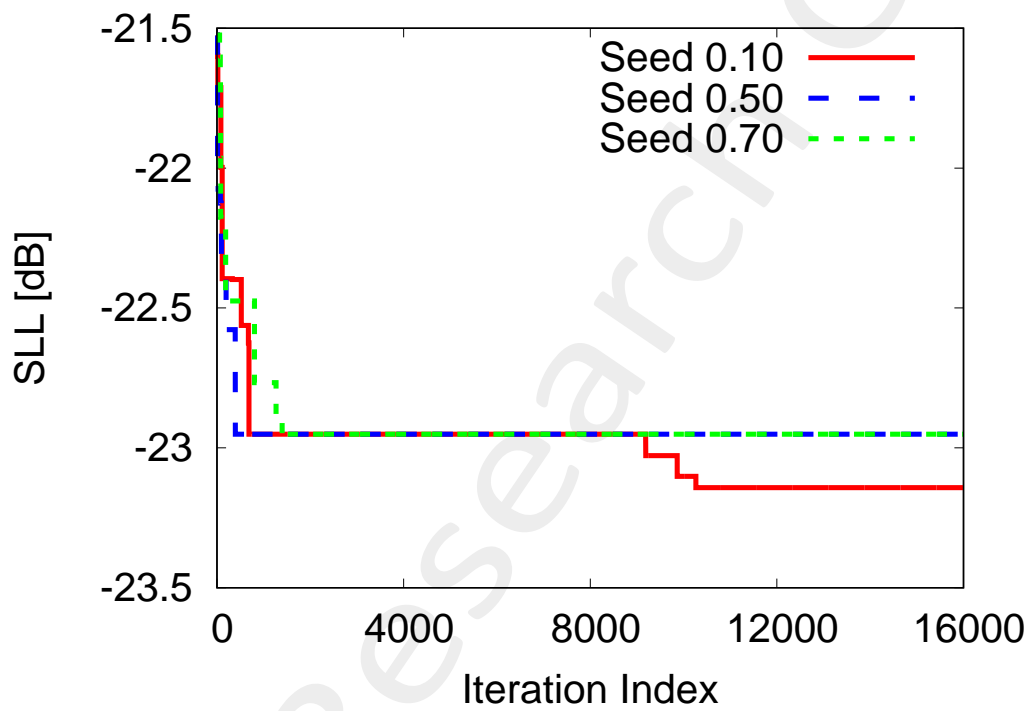


Figure 8: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 120$ ,  $q = 120$ ,  $J = 14400$ ) -  $SLL$  vs. Iterations.

### Statistics

	Max	Min	Mean	Variance
$SLL [dB]$	-21.51	-23.10	-22.91	$2.29 \times 10^{-2}$

Table V: Runs Statistics

Direction ( $\theta = 0^\circ, \phi = 0^\circ$ )

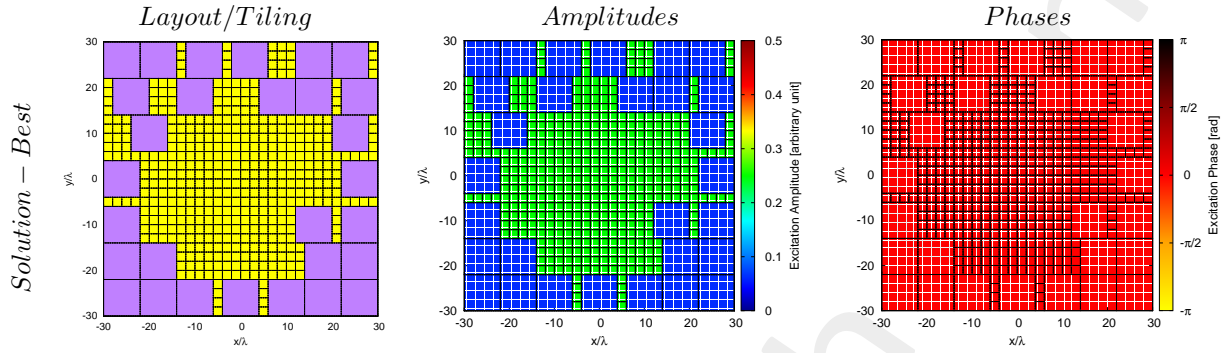


Figure 9: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Tiling configuration and weights coefficients value.

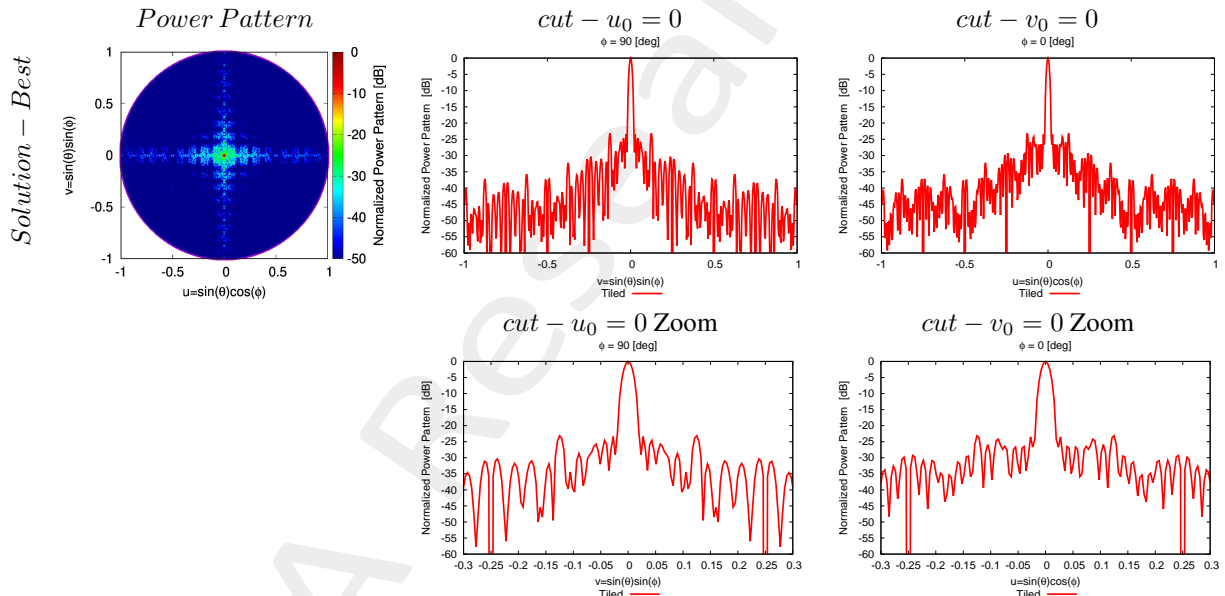


Figure 10: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Power patterns of the solutions.

	SLL [dB]	D [dBi]	HPBW <sub>az</sub> [deg]	HPBW <sub>el</sub> [deg]
<i>Solution – Best</i>	-23.10	45.12	0.98	1.00

Table VI: Pattern descriptors for the presented solutions.

Direction ( $\theta = 5^\circ, \phi = 0^\circ$ )

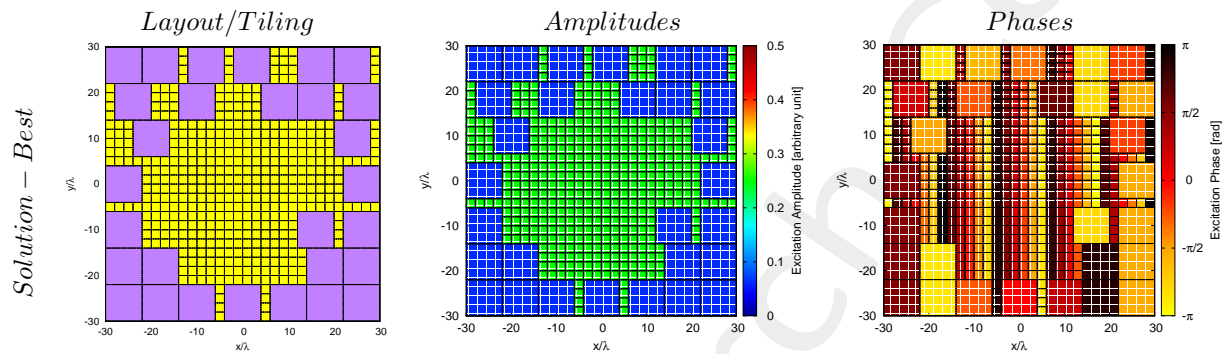


Figure 11: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Tiling configuration and weights coefficients value.

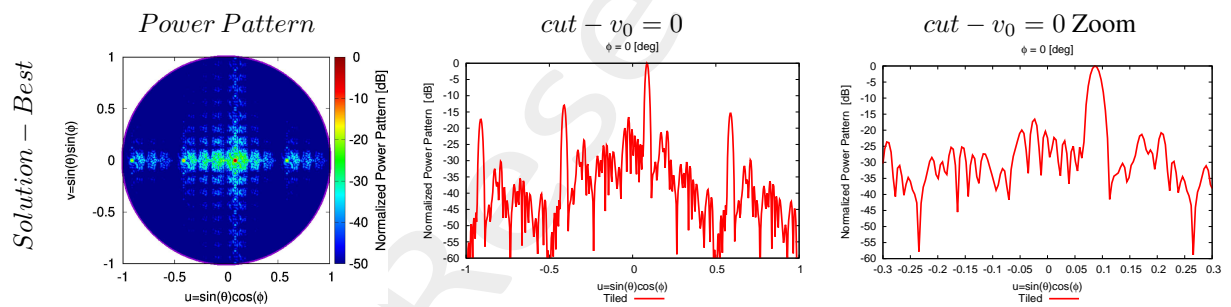


Figure 12: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]
<i>Solution – Best</i>	-12.93	43.34	1.05	1.08

Table VII: Pattern descriptors for the presented solutions.

Direction ( $\theta = 5^\circ, \phi = 90^\circ$ )

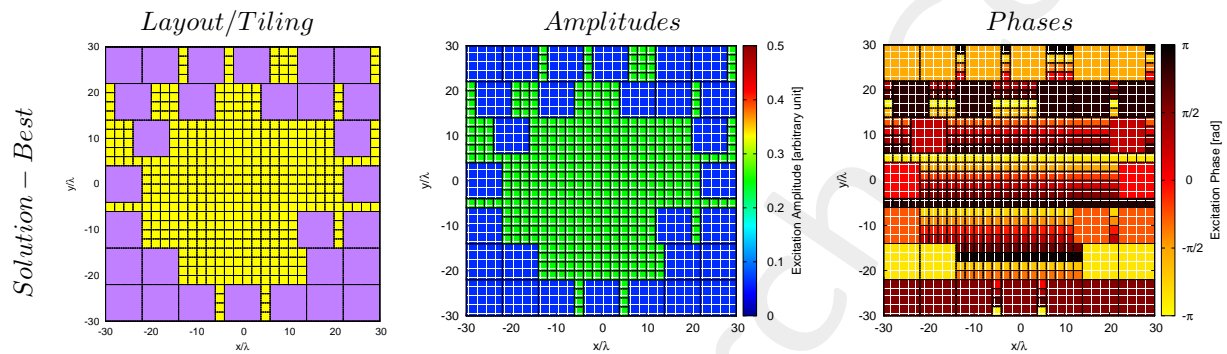


Figure 13: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Tiling configuration and weights coefficients value.

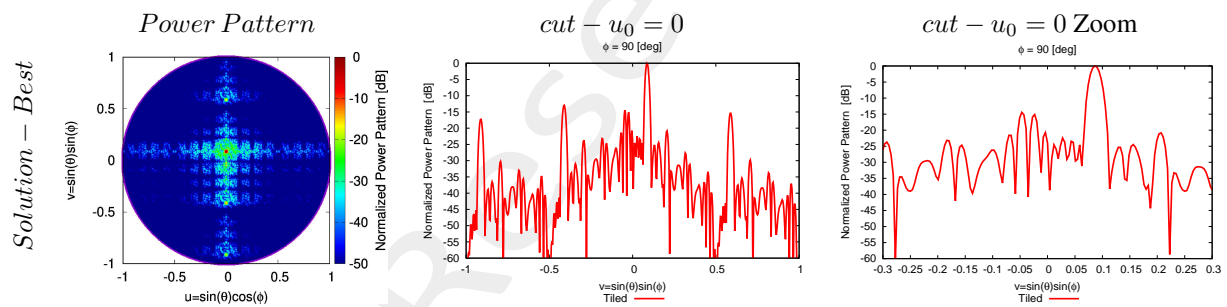


Figure 14: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda], k = 120, q = 120, J = 14400$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]
<i>Solution – Best</i>	-12.92	43.34	1.04	1.09

Table VIII: Pattern descriptors for the presented solutions.

### 3 Comparative Results

#### 3.1 ETM - Domino Tiling vs. $(1 \times 1, 2 \times 2)$ -Tiling: Non-Isophoric Excitations

##### 3.1.1 Antenna Aperture Rectangle $5 \times 8$ Elements

###### Array Analysis Parameters:

- Total Number of Elements:  $J = 40$ ;
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 256;
- Number of Samples along  $v$ : 256;
- Steering Direction:  $(\theta_s, \phi_s) = \{(0^\circ, 0^\circ)\}$ ;
- Tapering: CP - Symmetric Mask;
- Main Lobe Window Width along  $u$ :  $MW_u = 0.7$  [u];
- Main Lobe Window Width along  $v$ :  $MW_v = 1.10$  [v];
- Side Lobe levels:  $SLL_1 = -30$  [dB];

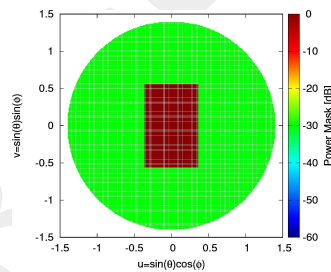


Figure 15: The power pattern mask used for the reference tapering optimization with *CP*.

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**Domino Tiling Parameters:**

- Tile: Domino;
- Clustering Ratio: 1 : 2;
- Total Number of Configurations:  $\Gamma = 14824$ ;

**$(1 \times 1, 2 \times 2)$ -Tiling Parameters:**

- *Small* Tile:  $S_1$ -tile:  $1 \times 1$ ;
- *Big* Tile:  $S_2$ -tile:  $2 \times 2$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 1;
- Clustering Ratio  $S_2$ -tile: 1 : 4;
- Total Number of Configurations:  $\Gamma = 16334$ ;



NUMERICAL RESULTS

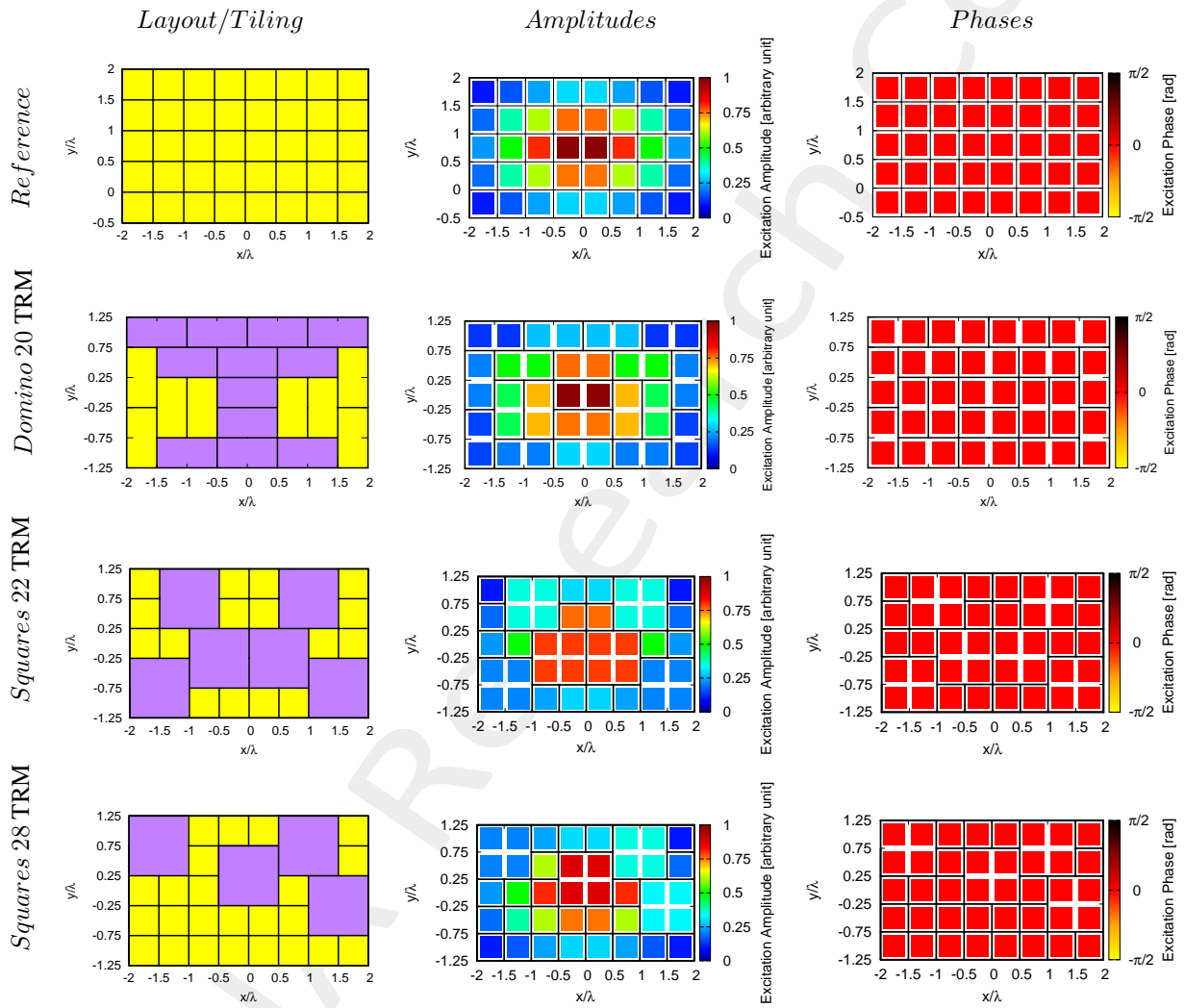


Figure 16: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 5$ ,  $q = 8$ ,  $J = 40$ ) - Tiling configuration and weights coefficients value.

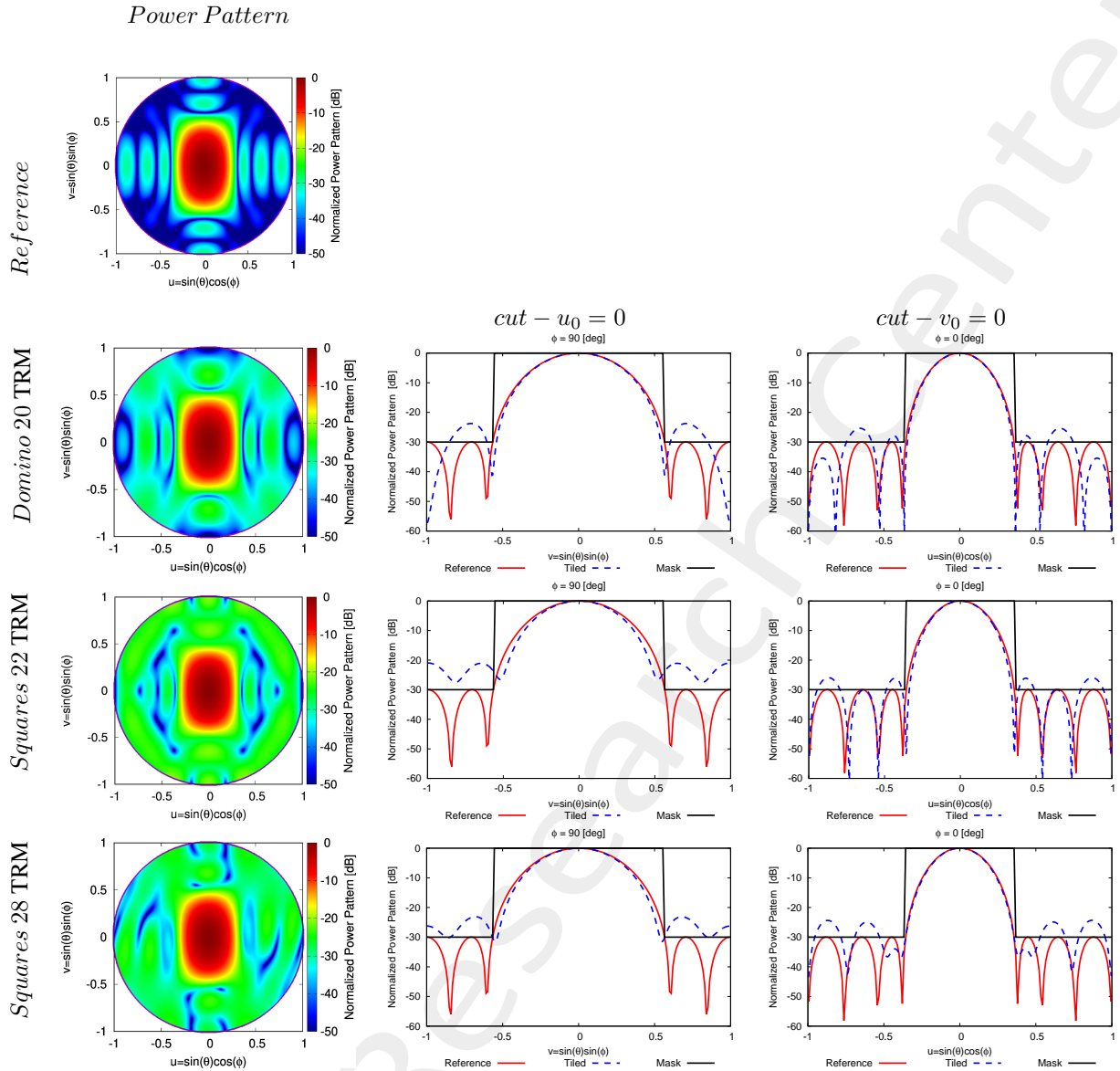


Figure 17: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 5$ ,  $q = 8$ ,  $J = 40$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]	TRM
<i>Reference</i>	-29.93	19, 36	16.43	26.39	40
<i>Domino</i>	-23.73	19.39	16.15	25.96	20
<i>Squares</i>	-20.94	19.37	15.88	24.46	22
<i>Squares</i>	-23.08	19.40	16.02	25.31	28

Table IX: Pattern descriptors for the presented solutions.

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## 3.2 ETM - Domino Tiling vs. Squares Tiling: Isophoric Excitations

### 3.2.1 Antenna Aperture Rectangle $5 \times 8$ Elements

#### Array Analysis Parameters:

- Total Number of Elements:  $J = 40$ ;
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 256;
- Number of Samples along  $v$ : 256;
- Steering Direction:  $(\theta_s, \phi_s) = \{(0^\circ, 0^\circ)\}$ ;
- Tapering: Isophoric;

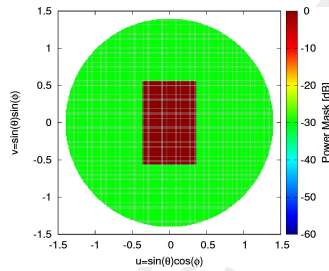


Figure 18: The power pattern mask used for the reference tapering optimization with  $CP$ .

#### Domino Tiling Parameters:

- Tile: Domino;
- Clustering Ratio: 1 : 2;
- Total Number of Configurations:  $\Gamma = 14824$ ;

#### $(1 \times 1, 2 \times 2)$ -Tiling Parameters:

- *Small* Tile:  $S_1$ -tile:  $1 \times 1$ ;
- *Big* Tile:  $S_2$ -tile:  $2 \times 2$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 1;
- Clustering Ratio  $S_2$ -tile: 1 : 4;
- Total Number of Configurations:  $\Gamma = 16334$ ;

NUMERICAL RESULTS

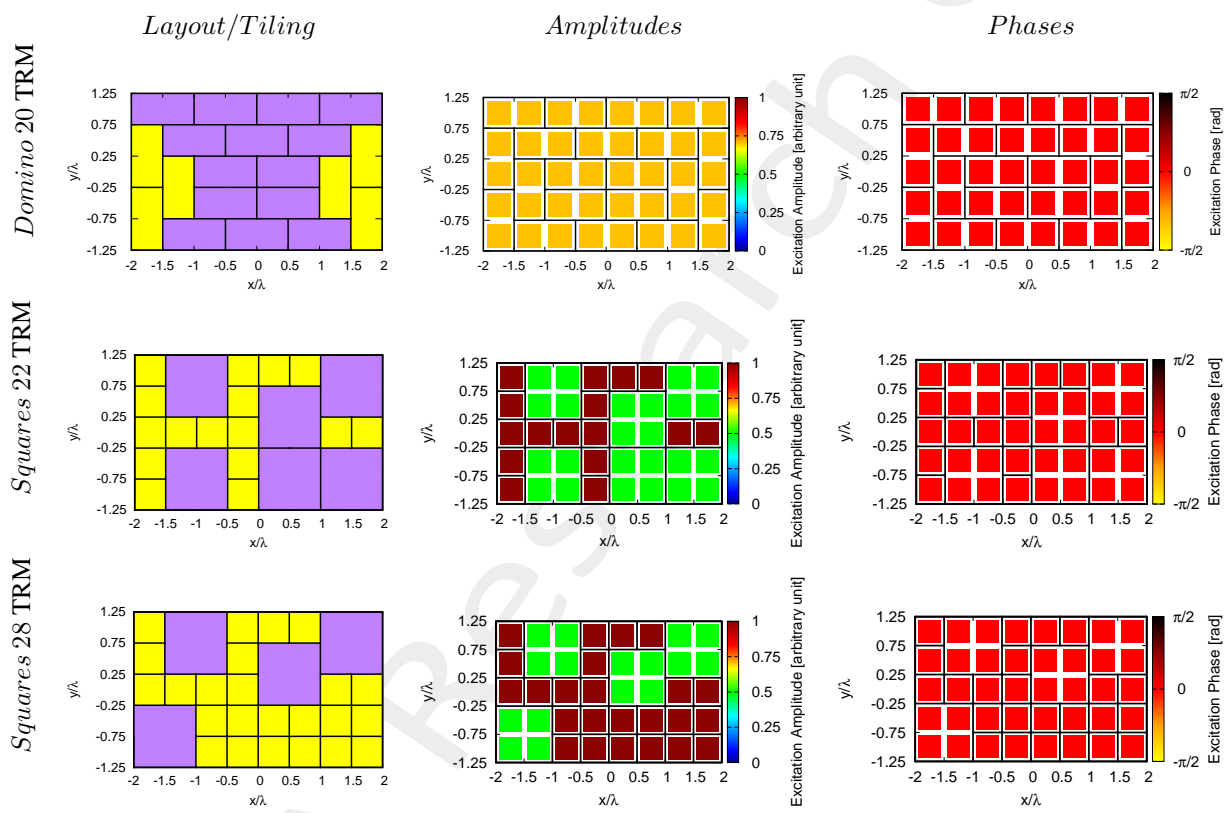


Figure 19: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 5$ ,  $q = 8$ ,  $J = 40$ ) - Tiling configuration and weights coefficients value.

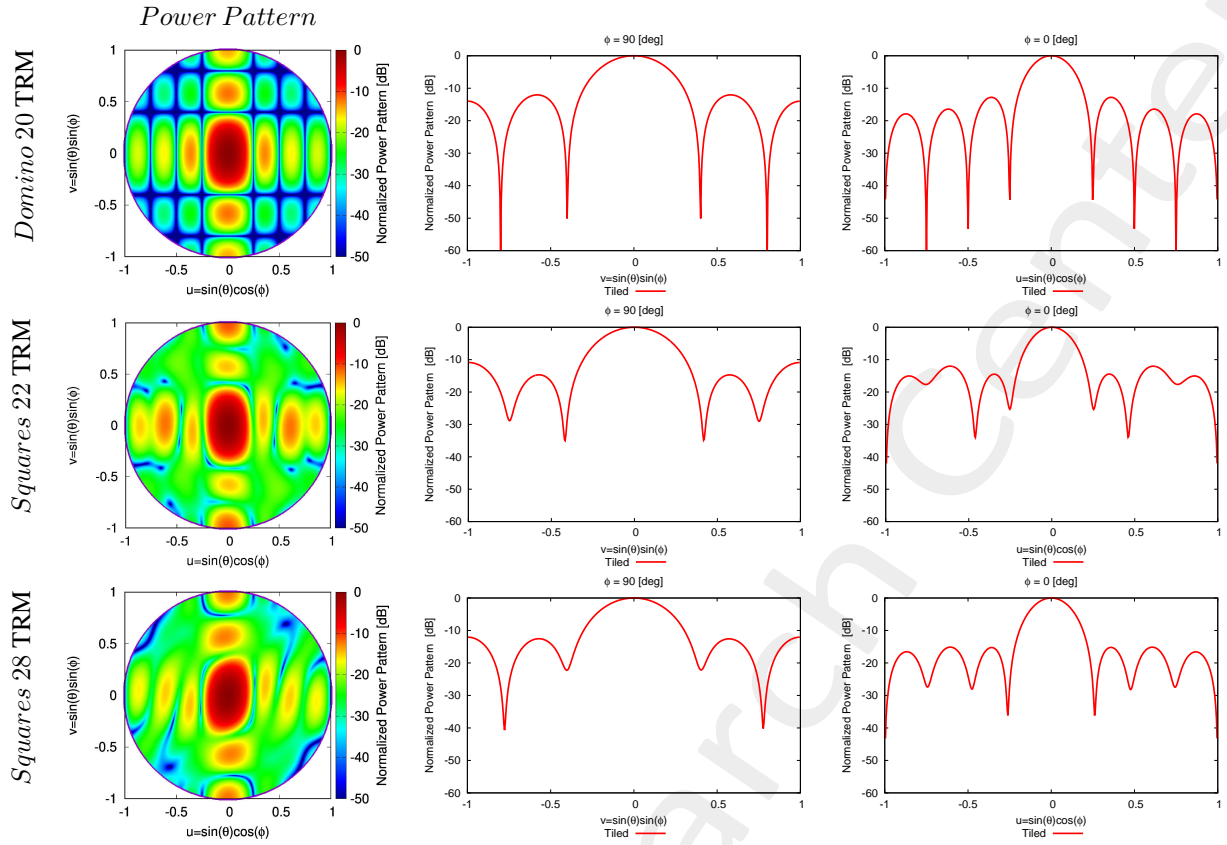


Figure 20: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 5$ ,  $q = 8$ ,  $J = 40$ ) - Power patterns of the solutions.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]	TRM
<i>Domino</i>	-12.04	20.49	12.08	20.77	20
<i>Squares</i>	-10.88	19.61	12.75	21.24	22
<i>Squares</i>	-12.04	19.90	13.07	20.89	28

Table X: Pattern descriptors for the presented solutions.

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### 3.3 Isophoric: n-tile Edge Size Analysis

#### 3.3.1 Antenna Aperture Rectangle $25 \times 25$ Elements

##### Optimization-based Tiling Method: Integer GA

###### Array Analysis Parameters:

- Total Number of Elements:  $J = 625$ ;
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 512;
- Number of Samples along  $v$ : 512;
- Steering Direction:  $(\theta_s, \phi_s) = \{(0^\circ, 0^\circ)\}$ ;
- Tapering: Isophoric;

###### Tiling Parameters:

- *Small* Tile:  $S_1$ -tile:  $1 \times 1$ ;
- *Big* Tile:  $S_2$ -tile:  $2 \times 2$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 1;
- Clustering Ratio  $S_2$ -tile:  $\{1 : 4, 1 : 9, 1 : 16, 1 : 25, 1 : 36\}$ ;

###### GA Parameters:

- GA type: *Integer Genetic Algorithm*;
- Population size:  $P = 60$ ;
- Crossover probability:  $p_{CR} = 0.9$ ;
- Mutation probability:  $p_M = 0.1$ ;
- Chromosome length:  $l = 20 - 24$ ;
- Maximum number of generations:  $K = 20000$ ;
- Maximum number of allowed TRM:  $TRM = 625$ ;
- Maximum number of functional evaluation calls:  $NFE = P \times K = 1.2 \times 10^6$ ;
- Number of initial Populations:  $N_{pop} = 1$ ;
- Number of GA random Seeds:  $N_{Seed} = 18$ ;
- Total number of Runs:  $N_{Runs} = N_{pop} \times N_{Seed} = 18$ ;

# NUMERICAL RESULTS

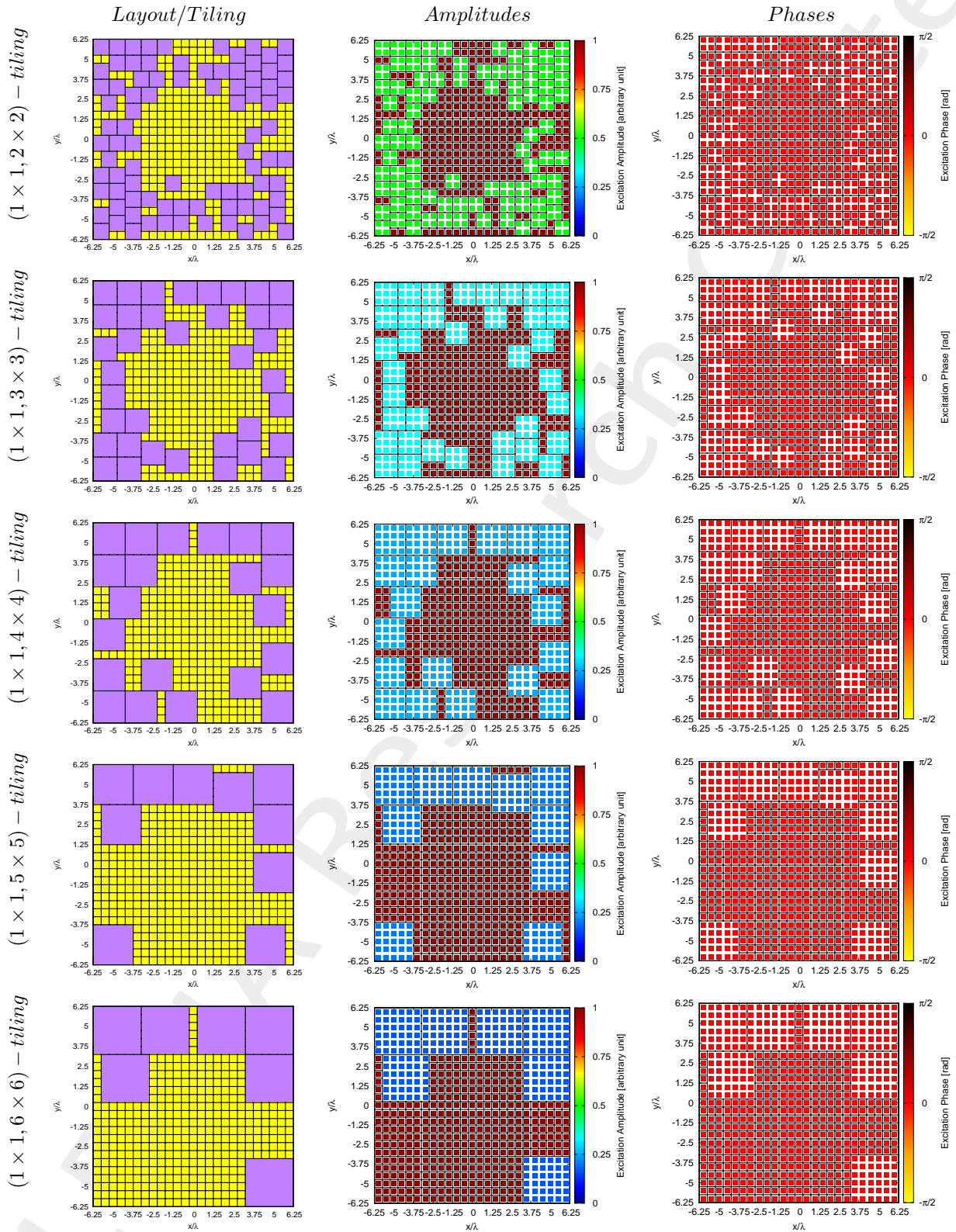


Figure 21: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 25$ ,  $q = 25$ ,  $J = 625$ ) - Tiling configuration and weights coefficients value.

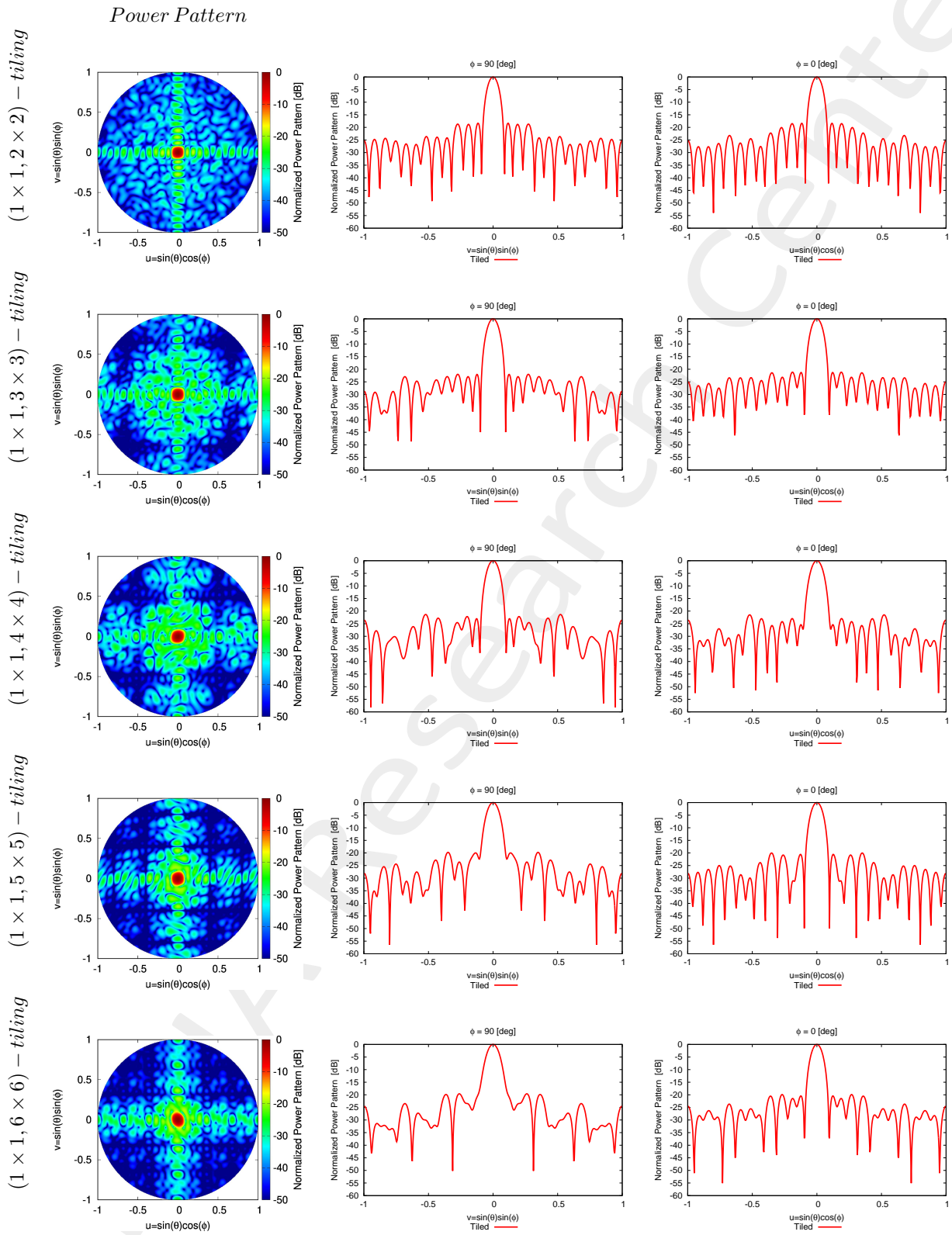


Figure 22: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 25$ ,  $q = 25$ ,  $J = 625$ ) - Power patterns of the solutions.



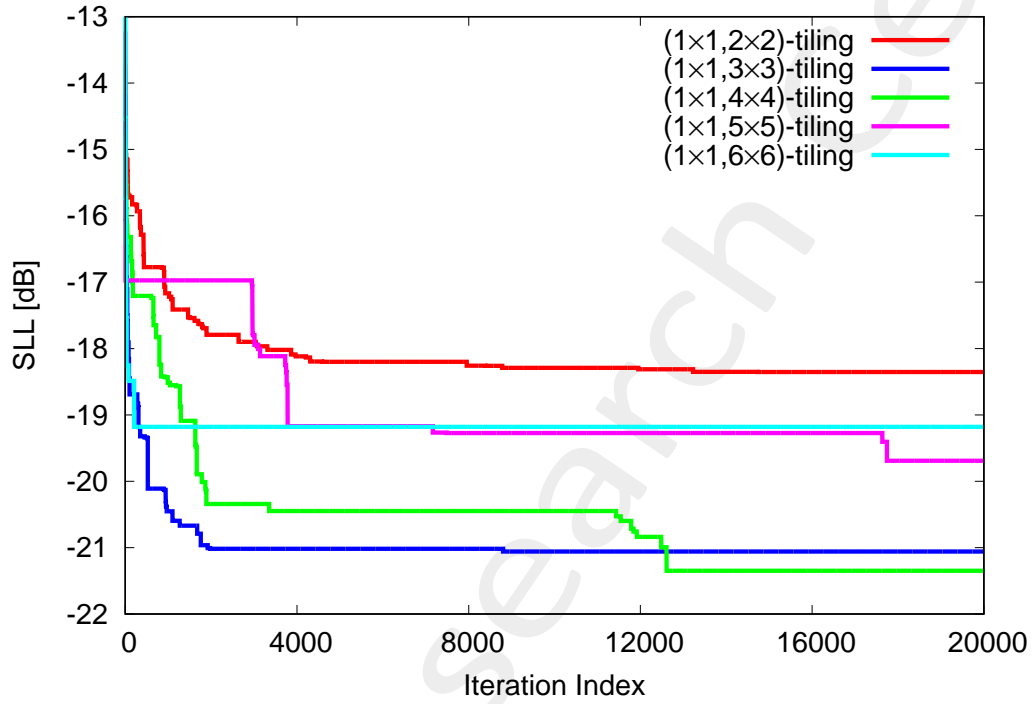


Figure 23: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 25$ ,  $q = 25$ ,  $J = 625$ ) -  $SLL$  vs. Iterations.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]	TRM
$(1 \times 1, 2 \times 2) - tiling$	-18.35	32.14	4.29	4.28	364
$(1 \times 1, 3 \times 3) - tiling$	-21.05	31.57	4.47	4.57	329
$(1 \times 1, 4 \times 4) - tiling$	-21.34	31.17	4.71	4.71	310
$(1 \times 1, 5 \times 5) - tiling$	-19.69	31.44	4.57	4.82	385
$(1 \times 1, 6 \times 6) - tiling$	-19.17	31.30	4.49	4.98	380

Table XI: Pattern descriptors for the presented solutions.

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### 3.3.2 Antenna Aperture Rectangle $30 \times 30$ Elements

#### Optimization-based Tiling Method: Integer GA

##### Array Analysis Parameters:

- Total Number of Elements:  $J = 900$ ;
- Spacing:  $d = \lambda/2$ ;
- Number of Samples along  $u$ : 512;
- Number of Samples along  $v$ : 512;
- Steering Direction:  $(\theta_s, \phi_s) = \{(0^\circ, 0^\circ)\}$ ;
- Tapering: Isophoric;

##### Tiling Parameters:

- *Small Tile*:  $S_1$ -tile:  $1 \times 1$ ;
- *Big Tile*:  $S_2$ -tile:  $2 \times 2$ ;
- Clustering Ratio  $S_1$ -tile: 1 : 1;
- Clustering Ratio  $S_2$ -tile: {1 : 4, 1 : 9, 1 : 16, 1 : 25, 1 : 36};

##### GA Parameters:

- GA type: *Integer Genetic Algorithm*;
- Population size:  $P = 60$ ;
- Crossover probability:  $p_{CR} = 0.9$ ;
- Mutation probability:  $p_M = 0.1$ ;
- Chromosome length:  $l = 25 - 29$ ;
- Maximum number of generations:  $K = 20000$ ;
- Maximum number of allowed TRM:  $TRM = 900$ ;
- Maximum number of functional evaluation calls:  $NFE = P \times K = 1.2 \times 10^6$ ;
- Number of initial Populations:  $N_{pop} = 1$ ;
- Number of GA random Seeds:  $N_{Seed} = 18$ ;
- Total number of Runs:  $N_{Runs} = N_{pop} \times N_{Seed} = 18$ ;

NUMERICAL RESULTS

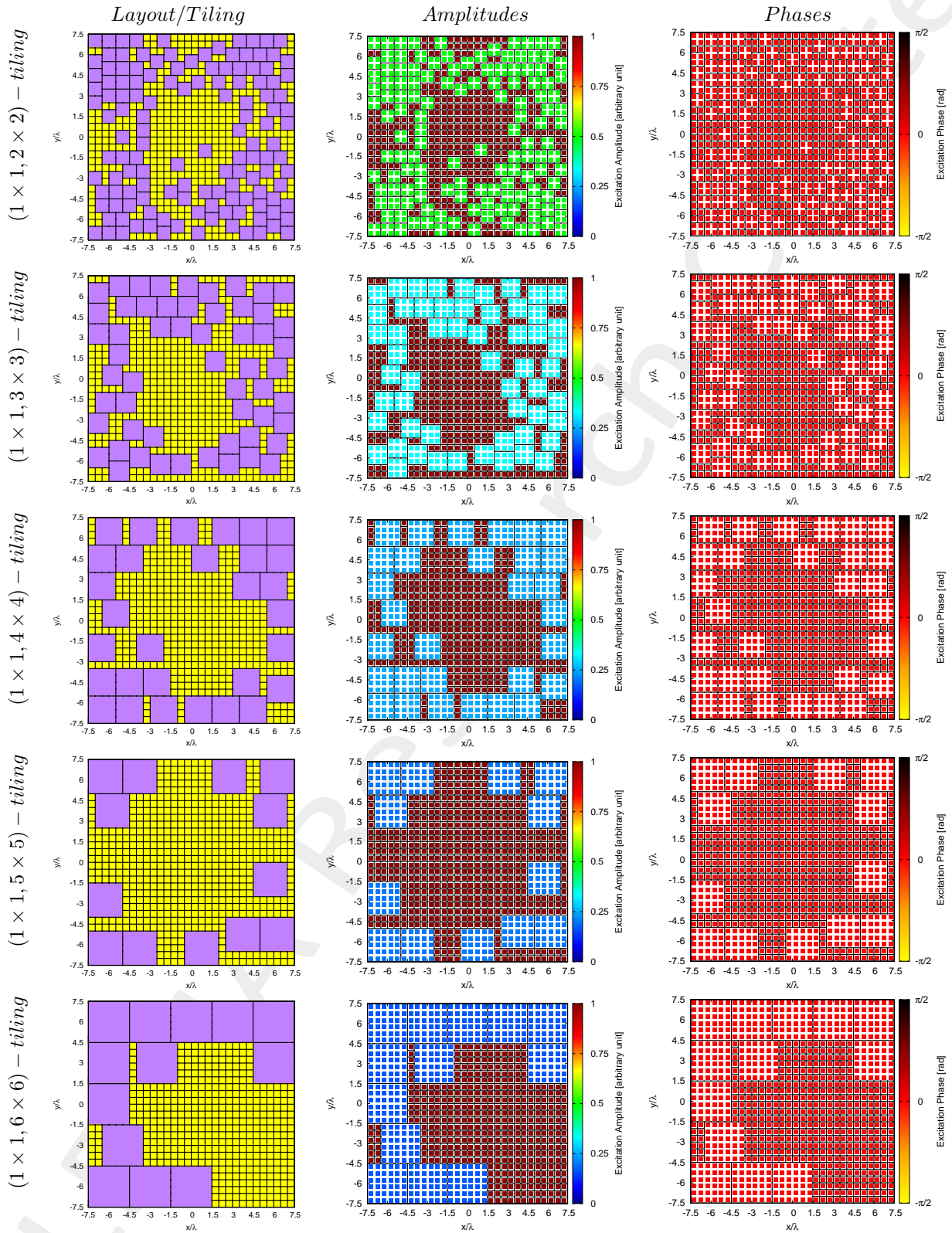


Figure 24: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 30$ ,  $q = 30$ ,  $J = 900$ ) - Tiling configuration and weights coefficients value.

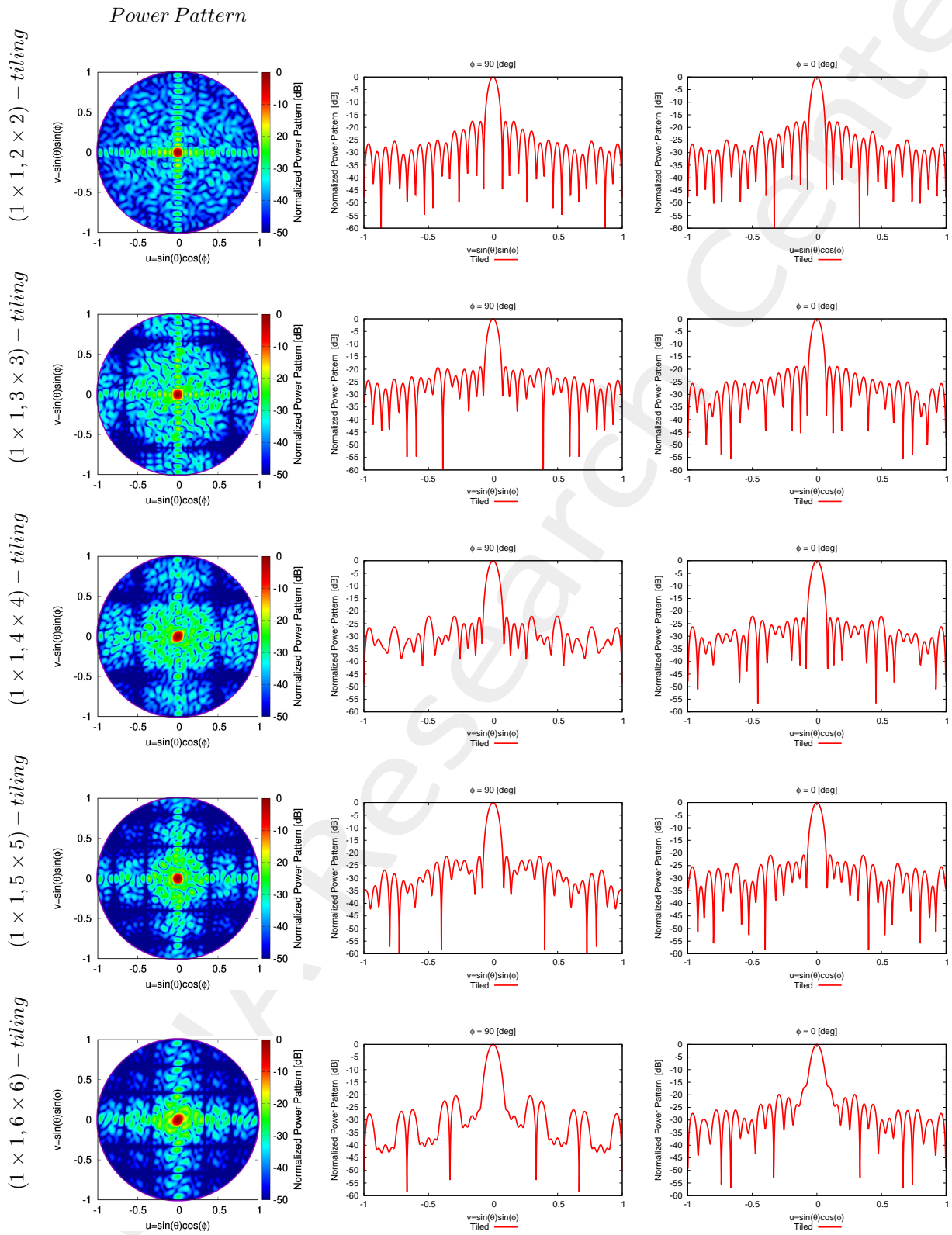


Figure 25: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 30$ ,  $q = 30$ ,  $J = 900$ ) - Power patterns of the solutions.

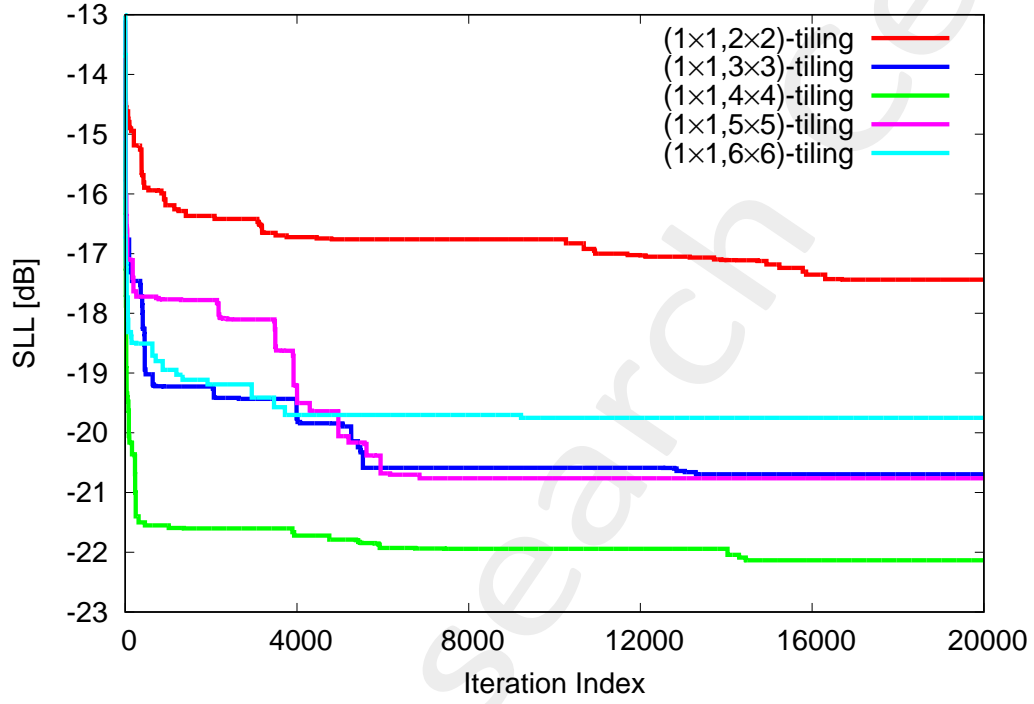


Figure 26: Numerical Assessment ( $d_x = d_y = 0.5 [\lambda]$ ,  $k = 30$ ,  $q = 30$ ,  $J = 900$ ) -  $SLL$  vs. Iterations.

	$SLL$ [dB]	$D$ [dBi]	$HPBW_{az}$ [deg]	$HPBW_{el}$ [deg]	TRM
$(1 \times 1, 2 \times 2) - tiling$	-18.15	33.79	3.55	3.55	516
$(1 \times 1, 3 \times 3) - tiling$	-20.65	33.13	3.68	3.66	476
$(1 \times 1, 4 \times 4) - tiling$	-22.12	32.88	3.86	3.94	465
$(1 \times 1, 5 \times 5) - tiling$	-20.76	33.14	3.78	3.80	588
$(1 \times 1, 6 \times 6) - tiling$	-19.67	32.49	3.89	4.24	445

Table XII: Pattern descriptors for the presented solutions.

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## 4 Conclusions

In the next years phased arrays are expected to be widely used for the new generation of communication systems. The research in this field is pushing towards the study of new design strategies capable of reducing the high production costs of these antennas while providing a simple and effective architecture.

In accordance with market trends, this thesis proposes an innovative modular strategy for the design of planar phased arrays. The presented approach provides a complete and irregular array layout using two square tiles of different sizes. Starting from analysis of covering theorems derived in field of mathematics, an enumerative approach, the ETM, able to retrieve the optimal tiling while providing the total aperture coverage with the best radiation performance has been developed in order to deal with the synthesis of low/medium-size rectangular arrays. Subsequently, a method based on optimization, the OTM, has been developed to address the synthesis of large arrays. Since the cardinality of the problem increases as the aperture of the array increases, the OTM exploits a *smart* coding technique able to provides a substantial reduction of the research space dimension.

The ETM and the OTM have been numerically validated and tested. The numerical analysis is aimed both at the general application level (using non-isophoric excitations) and in the specific field of satellite communications (using isophoric excitations).

### Evidence

- Thanks to the exhaustive exploration of the solutions space, the ETM method is able to find the optimal solution (or a set of optimal solutions, MOPs) that provides the minimum/maximize the desired objective (or objectives, MOPs). Furthermore, the total coverage of the surface is guaranteed by covering mathematical theory and the relative generalization;
- The coding used for the representation of the solutions/tilings in the OTM allows a substantial reduction of the research space. As a result, the large array synthesis that was computationally intractable is now affordable;

### Conclusions w.r.t. Clustered Arrays State of Art

With respect to *classical* clustering techniques which uses subarrays with arbitrary unconstrained shapes the proposed modular strategy ensures a simpler yet low cost antenna system. In fact, the “traditional” unconstrained clusters shapes do not guarantee to be physically contiguous and the associated feeding network can potentially become very complex and expensive.

Whereas, in comparison with the state of the art of tiled arrays, the following outcomes are stated:

1. The presented square-tiling approach, guarantees the optimal tiling of the antenna aperture using the available tiles. I.e. only tiles with predefined geometry has to be manufactured;
2. Unlike single shape tiling approaches in which the number of TRMs is fixed, multiple shapes tilings allows the designer to have control over the number of TRMs. This additional DoF can provide a wider range of candidate solutions;

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3. Moreover, multiple shapes tilings approaches enables better performance also in presence of isophoric excitations. This is due to the fact that they can provide more than just one amplitude quantization level (e.g. a set of  $m \times m$  and  $n \times n$  square tiles yields two amplitude quantization levels), which results is a sort of amplitude tapering;
  4. The usage of square tiles seems to enhance the steering performance over tiles with other geometric shapes (e.g. dominoes), at least for small scanning angles;

### Future Works

Future work should be aimed at improving the scanning performance of these arrays, as it is the main limiting factor. In this direction it could be interesting to analyze the use of:

- Multiple tiles: Use a set of tiles with more than two sizes in order to have different clustering ratios and multiple amplitude quantization levels, i.e. additional DoFs;
- Phase synthesis: Given the optimal tiling optimize the phase coefficients.
- *Tapered* tiles: Generate subarray pattern able to suppress the arising grating lobes, an thus boosting the scanning performance for a limited FoV. This can be achieved at the price of having a more complex module architecture (feeding network inside the module);
- Partial-subarrayed array: Move some control points at the subarray level while leave other at the element level give more control of the generated pattern;
- Meta-materials;

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More information on the topics of this document can be found in the following list of references.

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