

Robust Diagnosis of Microstrip Planar Phased Arrays Through a Compressive Sensing Approach

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Abstract

This work deals with the detection of faulty radiators in real microstrip patches planar phased arrays. Towards this goal, the diagnosis problem at hand is formulated within a probabilistic compressive sensing (CS) framework in order to avoid the fulfillment of the restricted isometry property (RIP) by the involved measurement operator. A customized Bayesian CS solution approach is then developed to yield robust and reliable guesses of the antenna under test (AUT) status by also taking into account all mutual coupling effects arising in realistic operative conditions. Some numerical benchmarks are shown to assess the effectiveness of the proposed diagnosis tool when considering a variation of the antenna size and failure rate, as well as a change of the amount of noise on processed far-field data.

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1 Numerical Assessment

1.1 Microstrip Array, $N = 144$ Elements

Parameters

- Gold Array
 - Frequency: $f = 3.6$ [GHz];
 - Number of elements along x and y : $N_x = N_y = 12$;
 - Total number of elements: $N = N_x \times N_y = 144$;
 - Spacing along x and y : $d_x = d_y = 0.5$ [λ];
 - Excitation tapering: Slepian [1];
 - Angular region at the receiver: $\Psi = \{(u, v) : -u_0 \leq u \leq u_0, -v_0 \leq v \leq v_0\}$, with $u_0 = v_0 = 0.1$ [1];

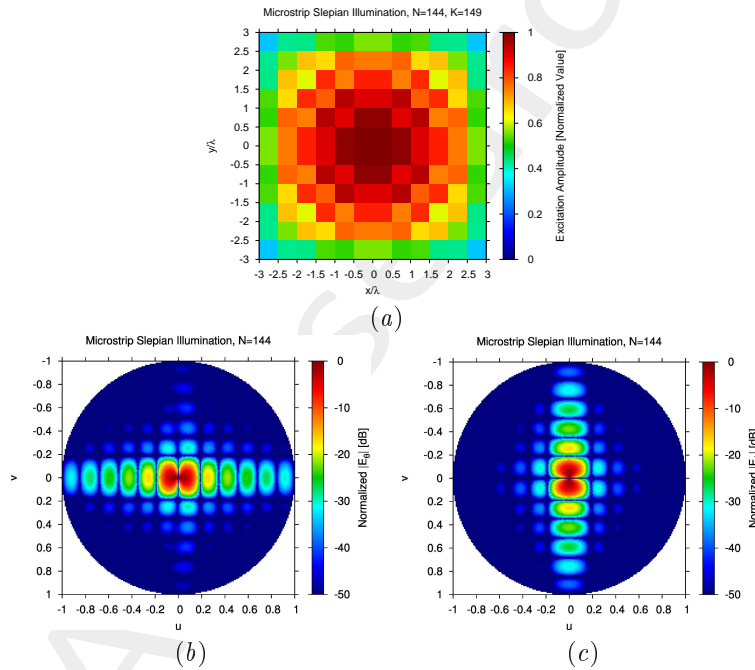


Figure 1: (a) Array excitations and normalized (b) $|E_\theta(u, v)|$ and (c) $|E_\phi(u, v)|$ patterns of the gold array.

- Failed Array
 - Failure factor: $\kappa = 0$ (total failures);
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
1	1%
3	2%
6	4%
12	8%
14	10%
17	12%
23	16%
29	20%

Table 1: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points along u and v : $K_u = K_v = 15$;
 - Number of points in the visible range: $K = 149$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

Results

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 1$) - Best and Worst *BCS* Reconstructions

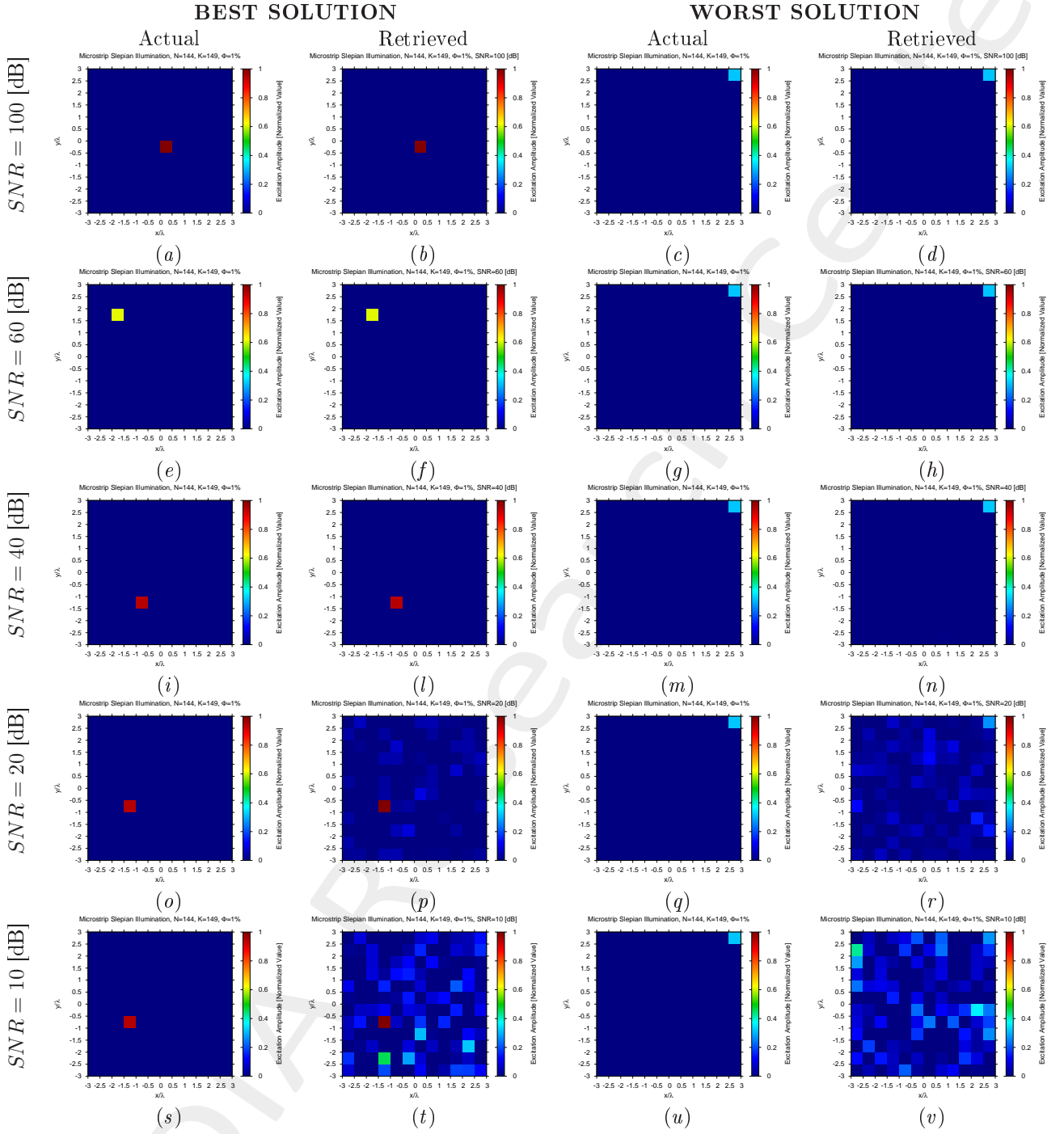


Figure 2: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 1\%$) - Best and worst reconstructions under several *SNR* values.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 3$) - Best and Worst *BCS* Reconstructions

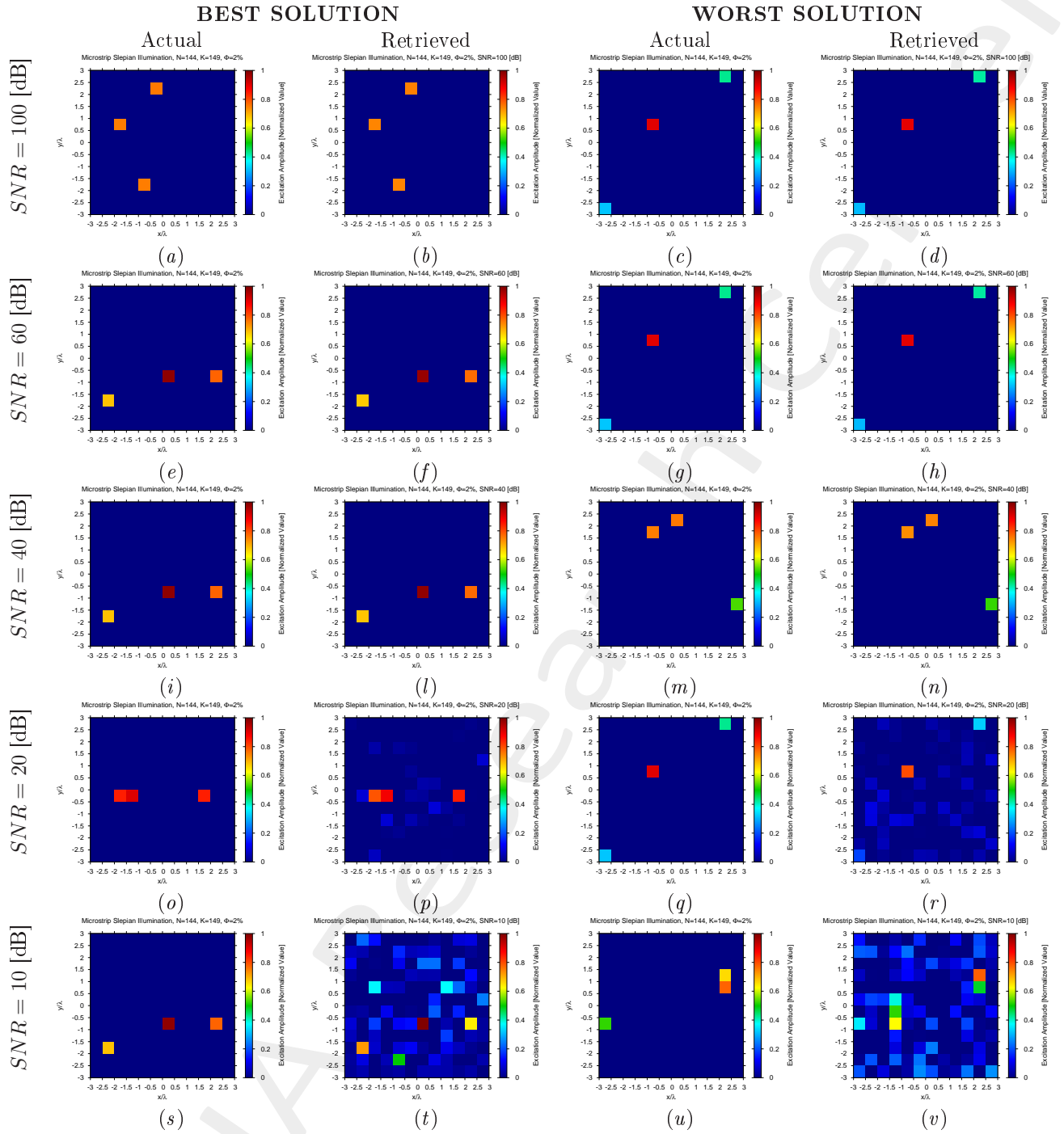


Figure 3: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 2\%$) - Best and worst reconstructions b under several *SNR* values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 6$) - Best and Worst *BCS* Reconstructions

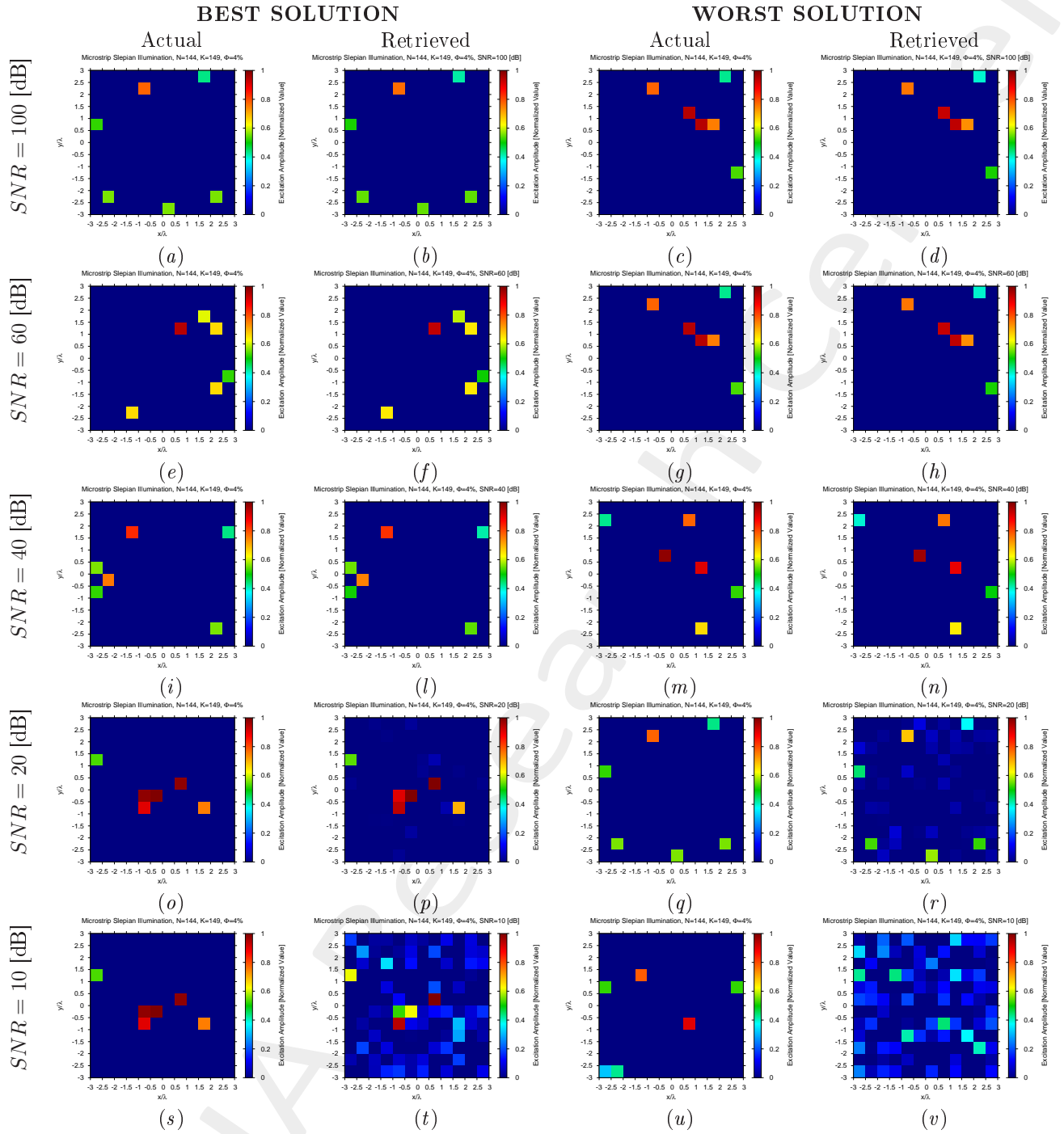


Figure 4: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 4\%$) - Best and worst reconstructions under several *SNR* values.

$\Phi = \frac{N_f}{N} = 8\%$ ($N_f = 12$) - Best and Worst *BCS* Reconstructions

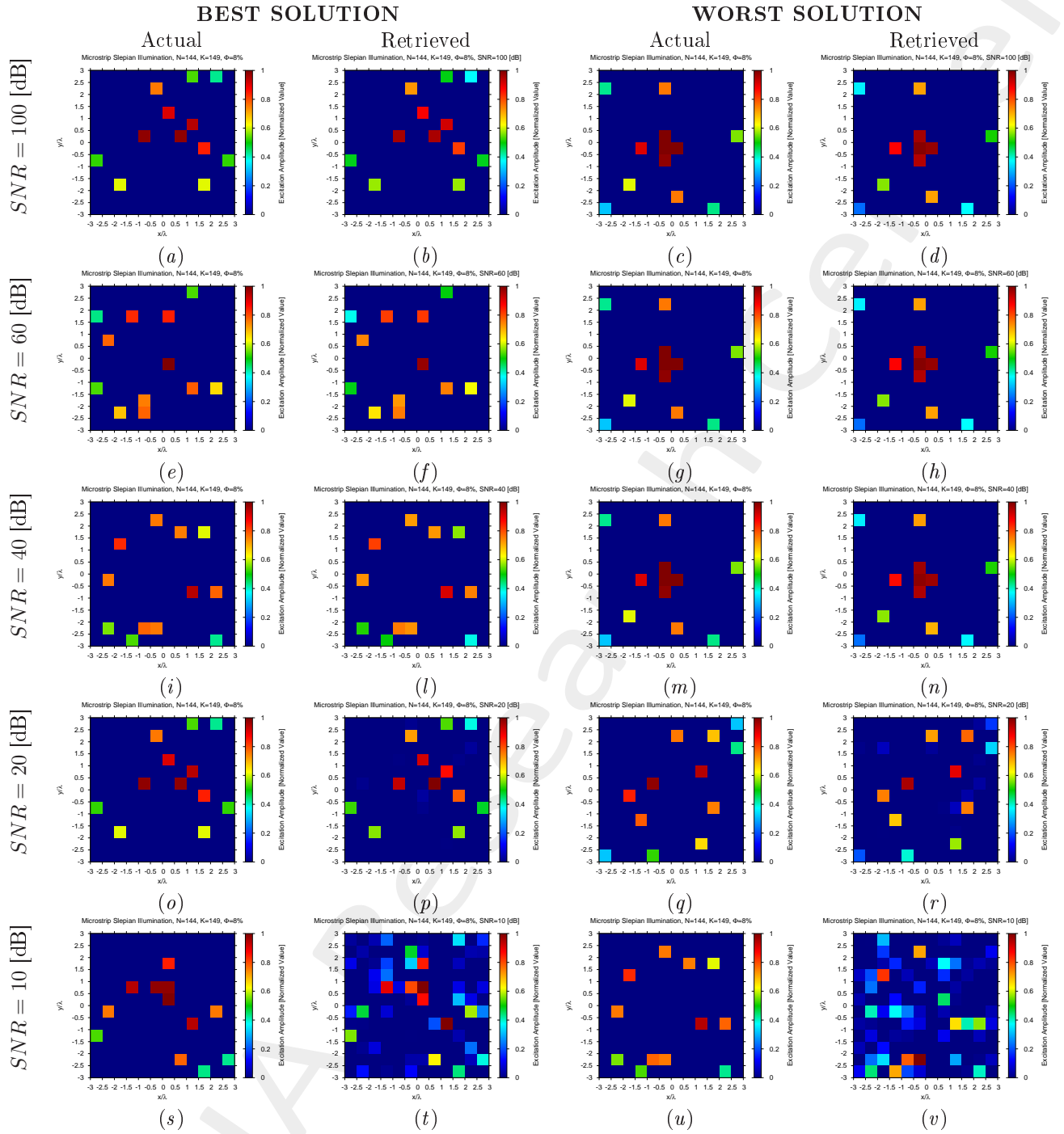


Figure 5: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 8\%$) - Best and worst reconstructions under several *SNR* values.

Diagnosis Error and Confidence Level

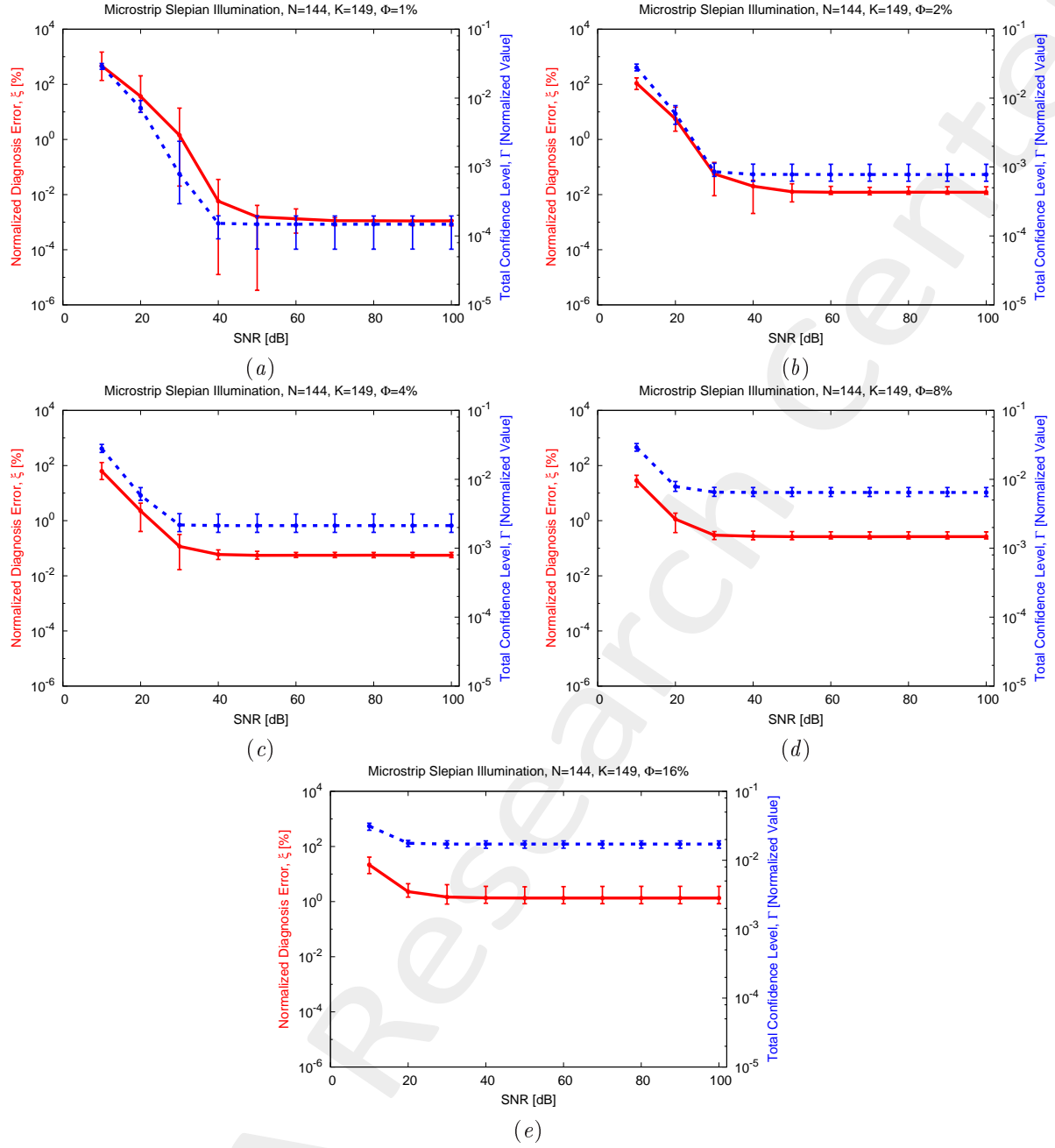


Figure 7: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the *SNR*, for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

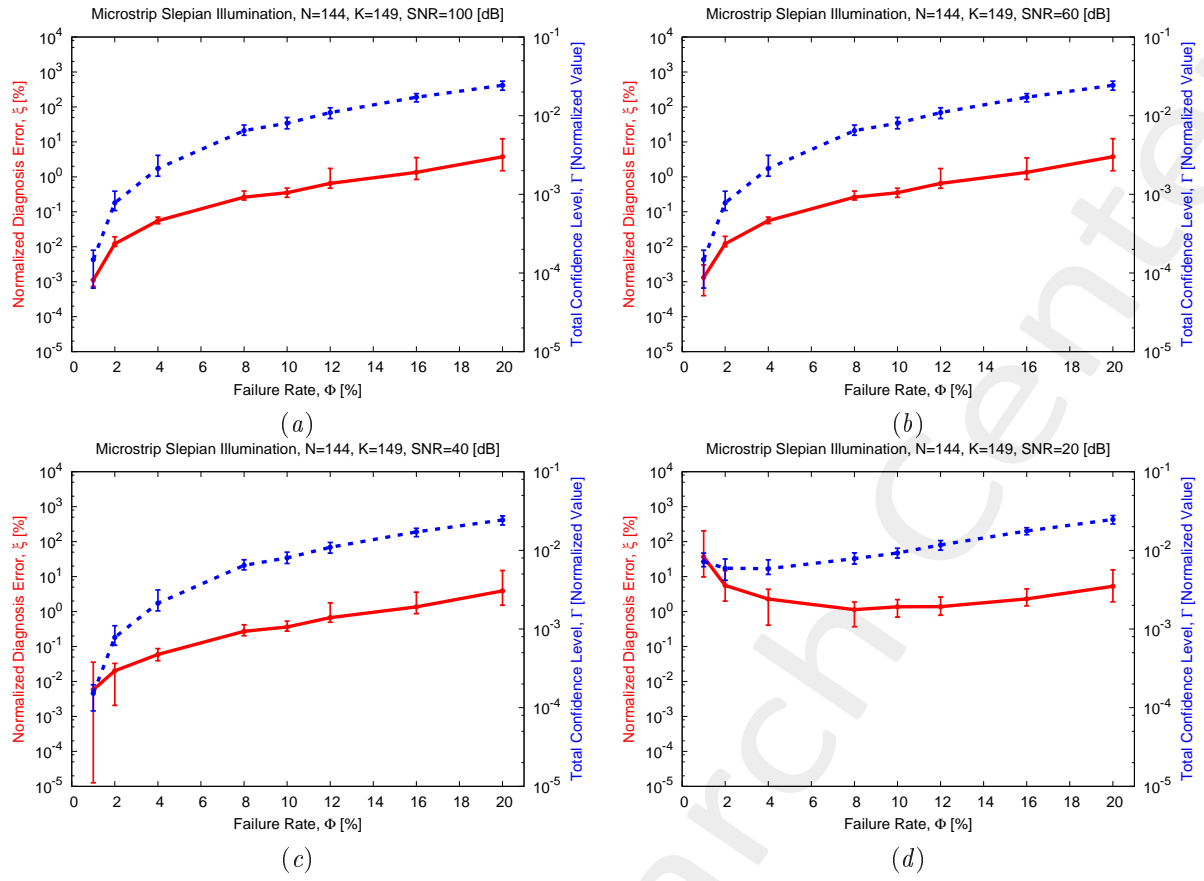


Figure 8: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

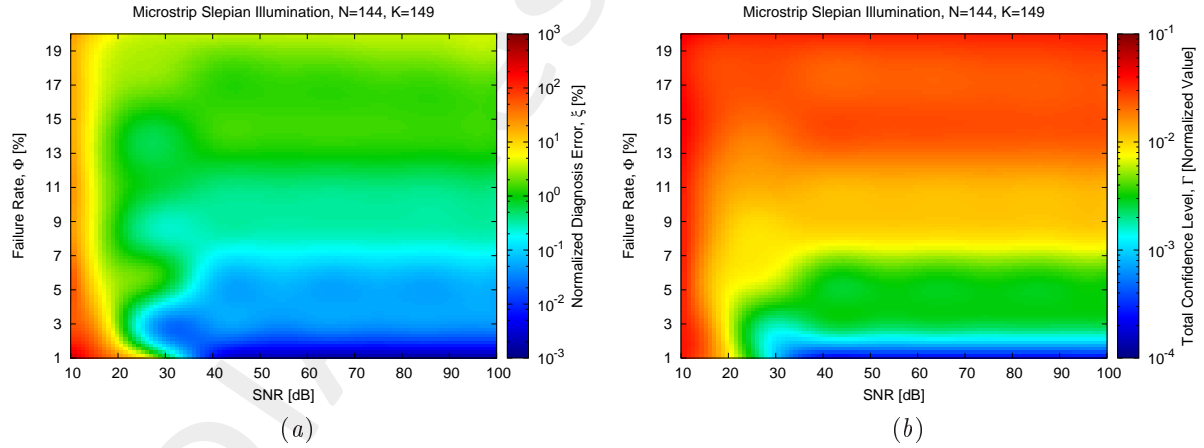


Figure 9: *Microstrip Patches Array* ($N = 144$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average diagnosis error (ξ) and total confidence level (Γ) versus the SNR and the failure rate (Φ).

1.2 Microstrip Array, $N = 324$ Elements

Parameters

- Gold Array
 - Frequency: $f = 3.6$ [GHz];
 - Number of elements along x and y : $N_x = N_y = 18$;
 - Total number of elements: $N = N_x \times N_y = 324$;
 - Spacing along x and y : $d_x = d_y = 0.5$ [λ];
 - Excitation tapering: Slepian [1];
 - Angular region at the receiver: $\Psi = \{(u, v) : -u_0 \leq u \leq u_0, -v_0 \leq v \leq v_0\}$, with $u_0 = v_0 = 0.1$ [1];

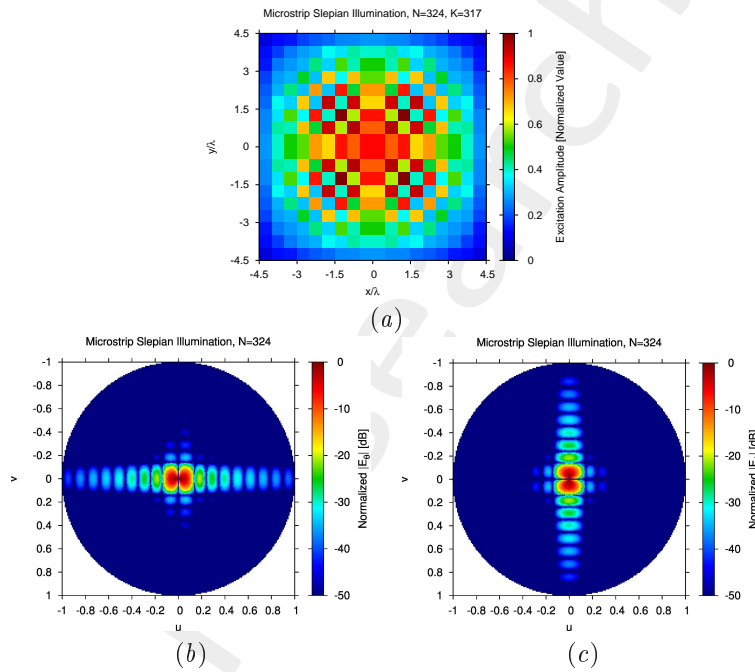


Figure 10: (a) Array excitations and normalized (b) $|E_\theta(u, v)|$ and (c) $|E_\phi(u, v)|$ patterns of the gold array.

- Failed Array
 - Failure factor: $\kappa = 0$ (total failures);
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
3	1%
6	2%
13	4%
26	8%
32	10%
39	12%
52	16%
65	20%

Table 2: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points along u and v : $K_u = K_v = 21$;
 - Number of points in the visible range: $K = 317$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

Results

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 3$) - Best and Worst *BCS* Reconstructions

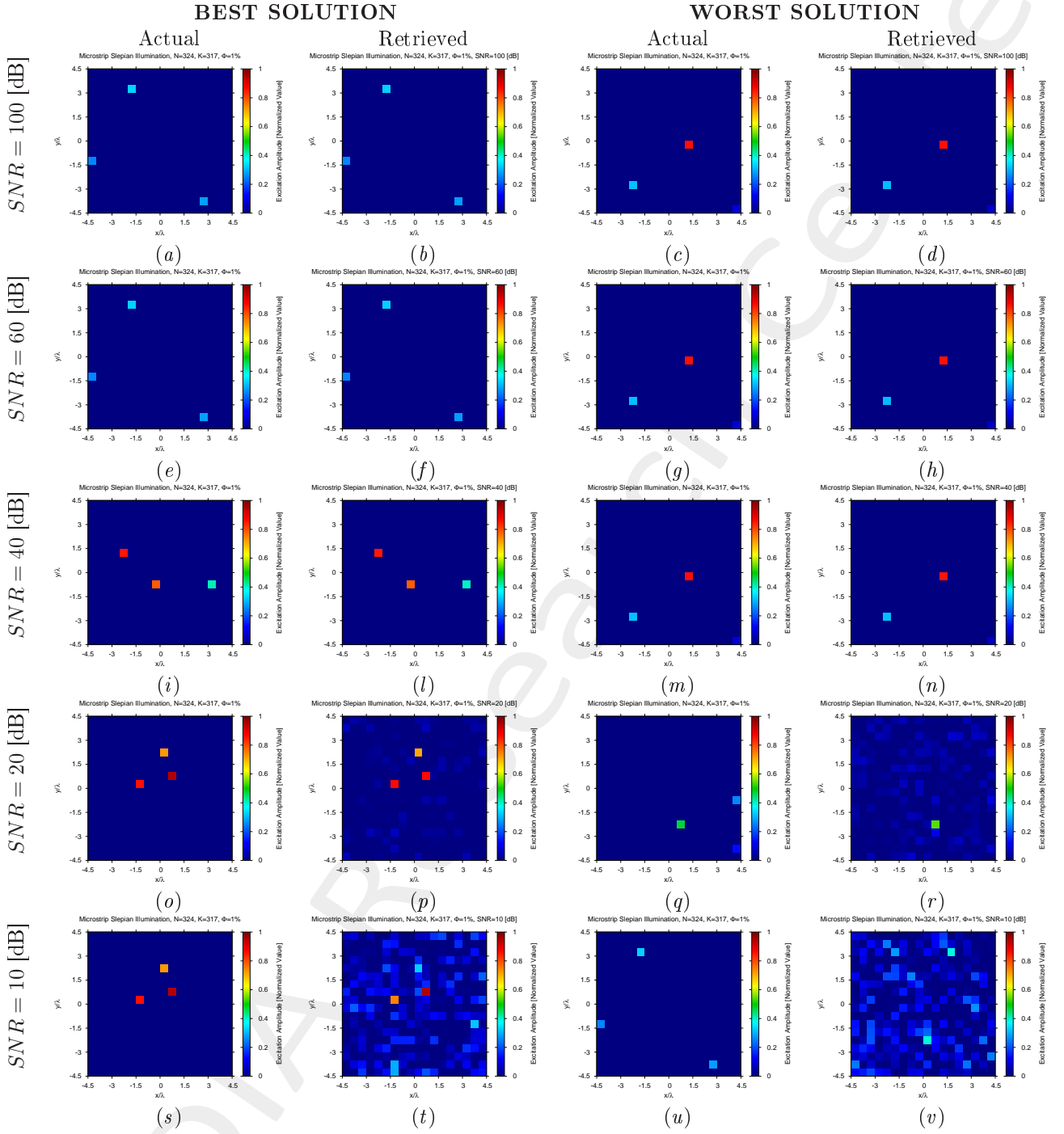


Figure 11: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 1\%$) - Best and worst reconstructions under several *SNR* values.

$$\Phi = \frac{N_f}{N} = 4\% \quad (N_f = 13) \text{ - Best and Worst } BCS \text{ Reconstructions}$$

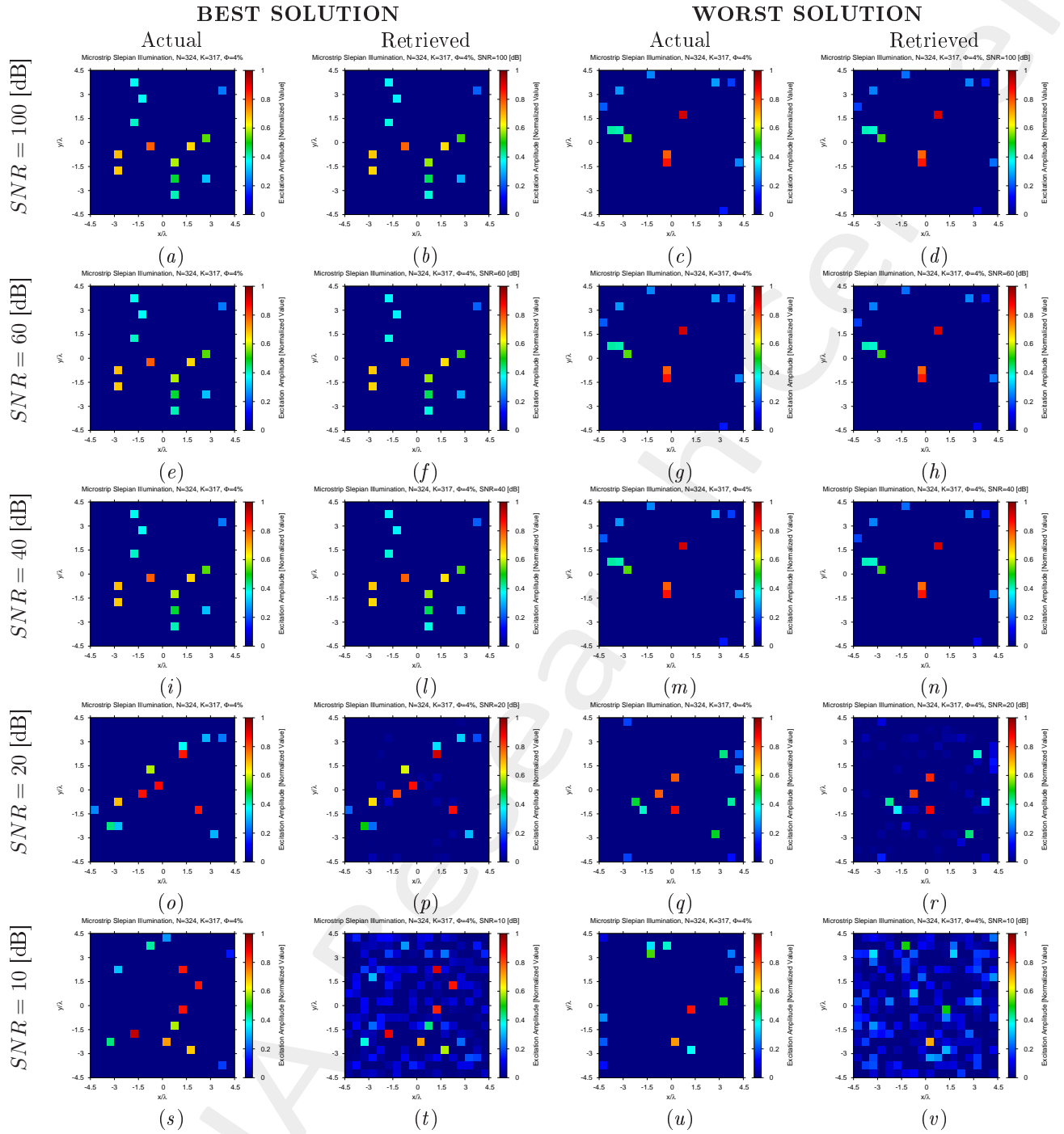


Figure 13: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 4\%$) - Best and worst reconstructions under several SNR values.

$$\Phi = \frac{N_f}{N} = 8\% \quad (N_f = 26) \text{ - Best and Worst } BCS \text{ Reconstructions}$$

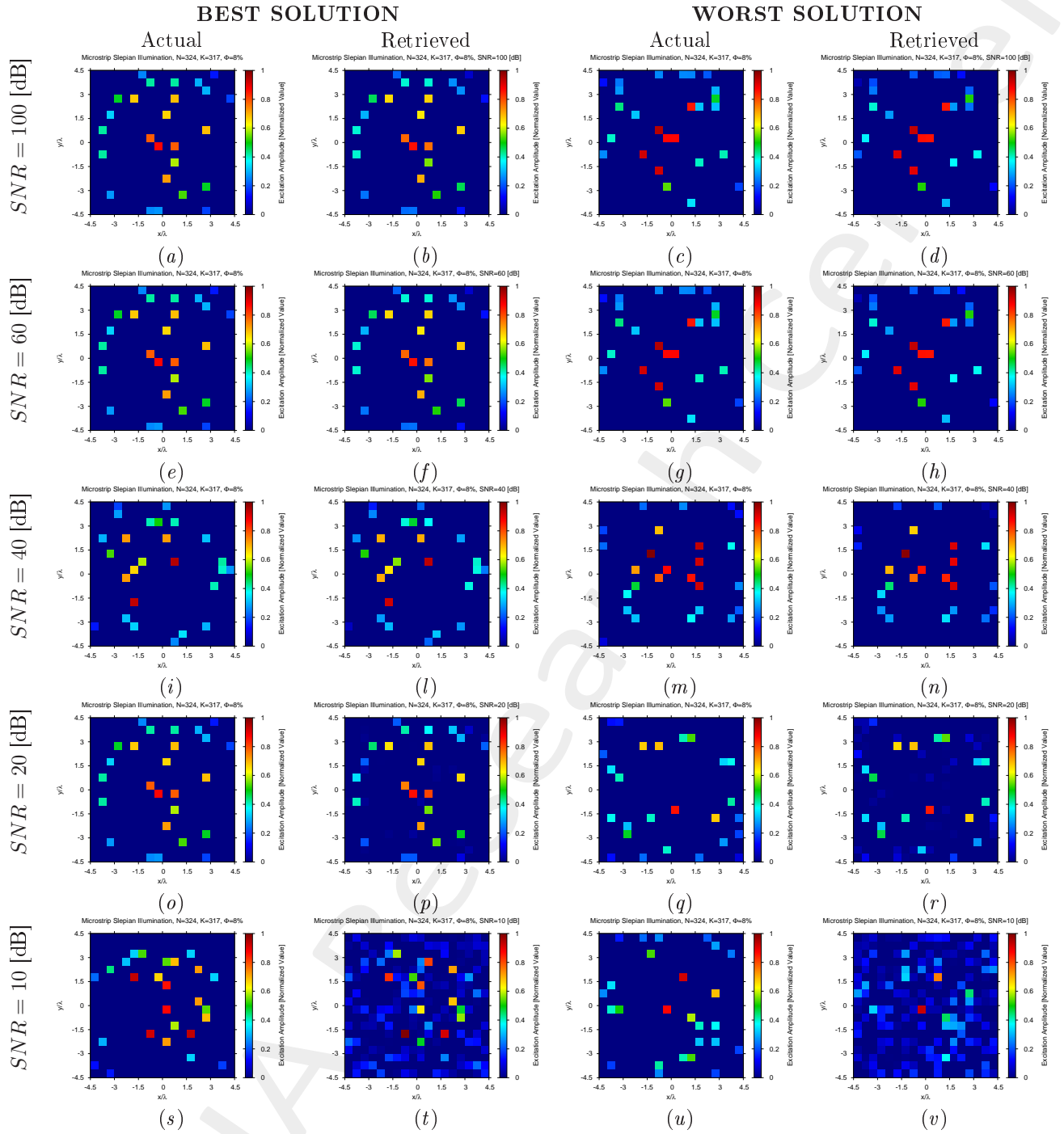


Figure 14: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 8\%$) - Best and worst reconstructions under several SNR values.

$\Phi = \frac{N_f}{N} = 16\%$ ($N_f = 52$) - Best and Worst *BCS* Reconstructions

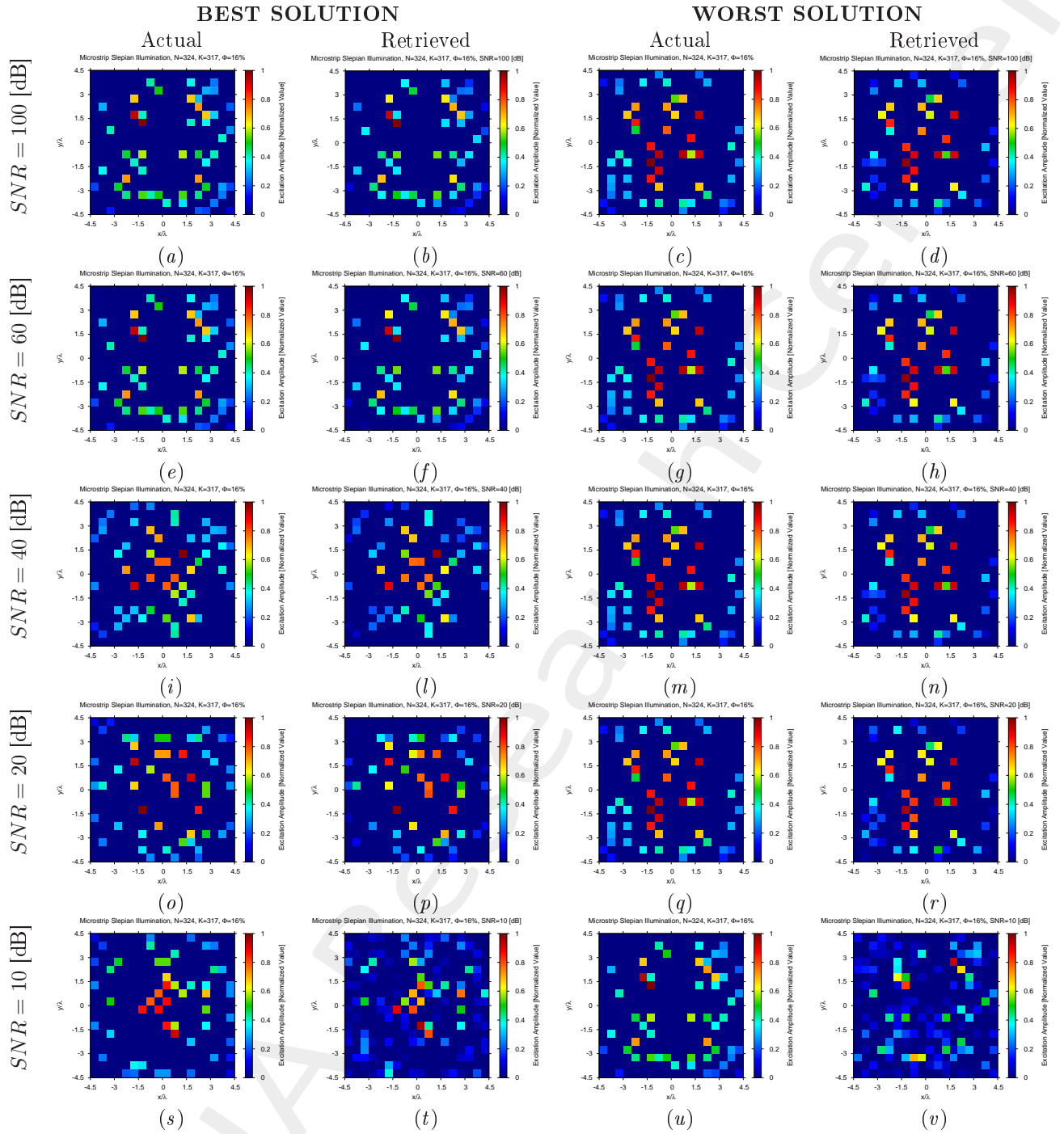


Figure 15: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 16\%$) - Best and worst reconstructions under several *SNR* values.

Diagnosis Error and Confidence Level

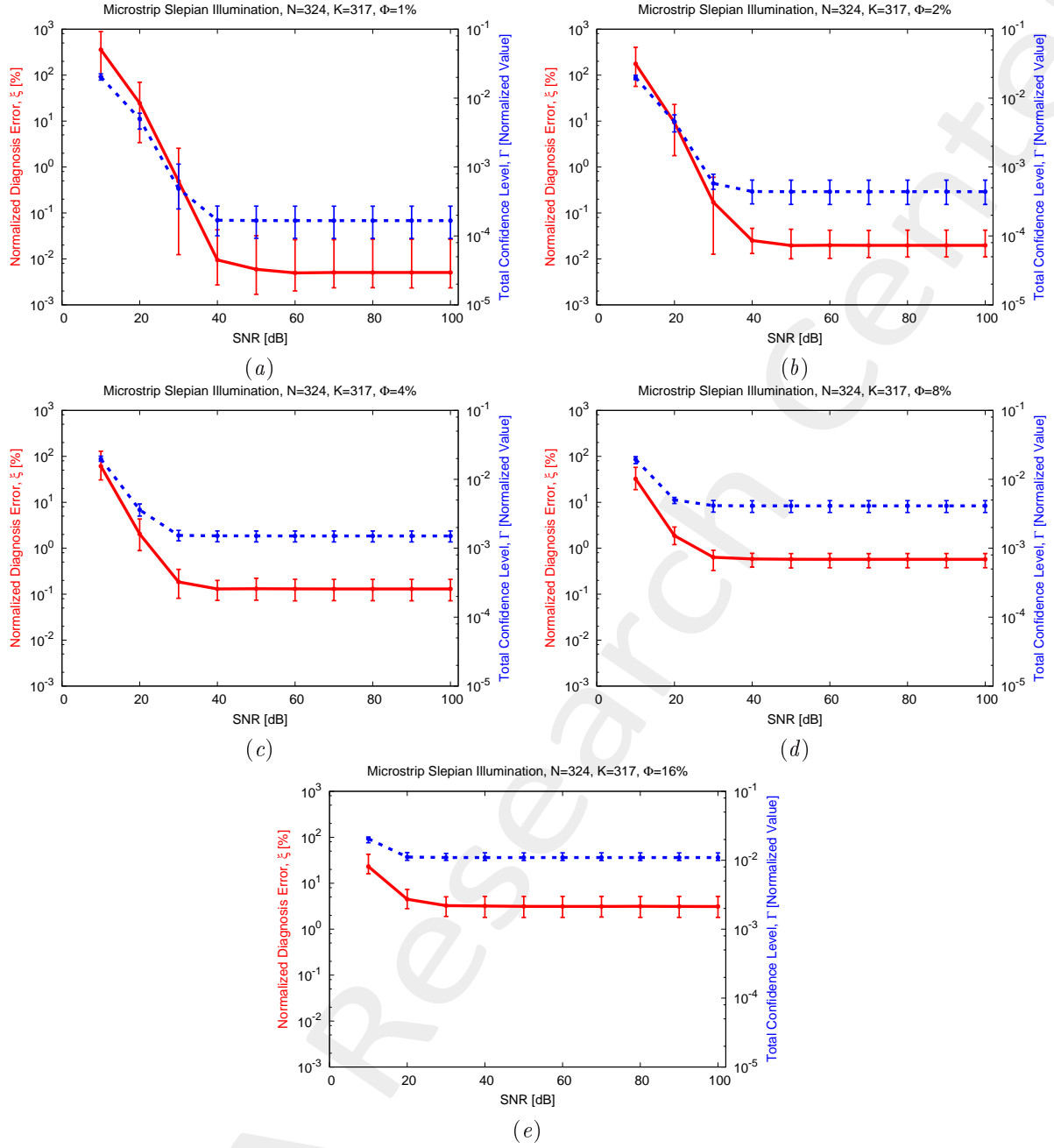


Figure 16: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the *SNR*, for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

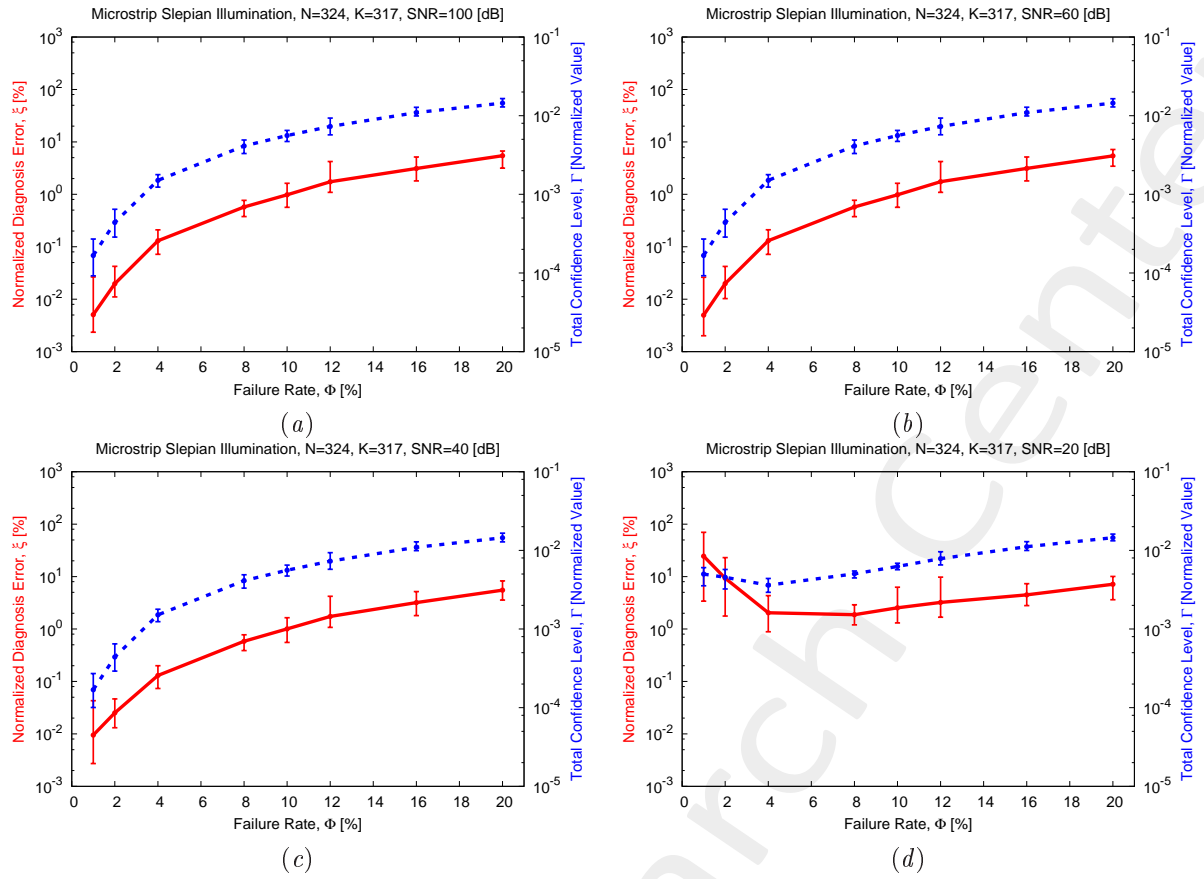


Figure 17: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

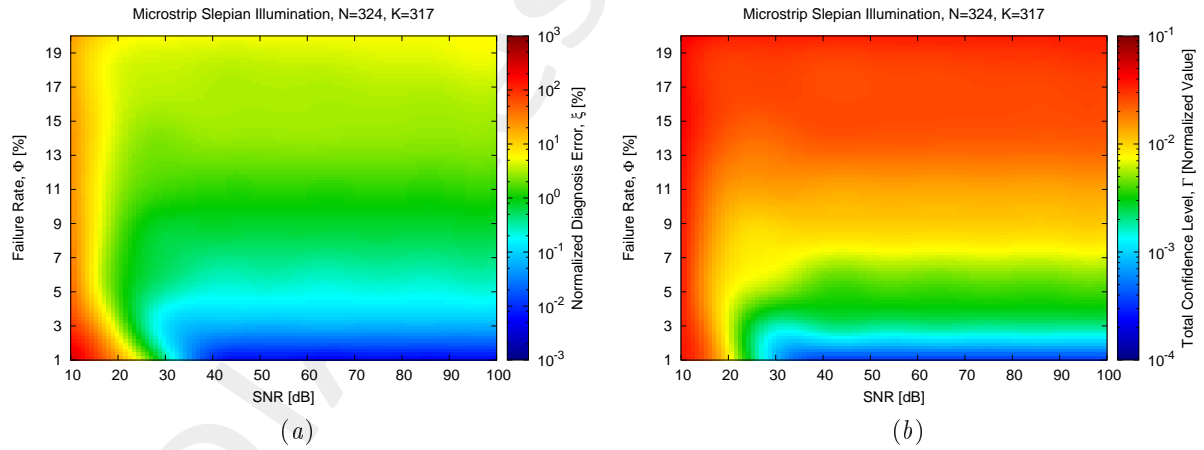


Figure 18: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$) - Behavior of the average diagnosis error (ξ) and total confidence level (Γ) versus the SNR and the failure rate (Φ).

1.3 Comparison vs Array Size (N)

The following figures summarize the diagnosis outcomes when considering a variation of the number of radiators, N . More precisely, Fig. 19 reports the average diagnosis error and confidence level when considering a failure rate of $\Phi = 4\%$, while results for $\Phi = 16\%$ are shown in Fig. 20.

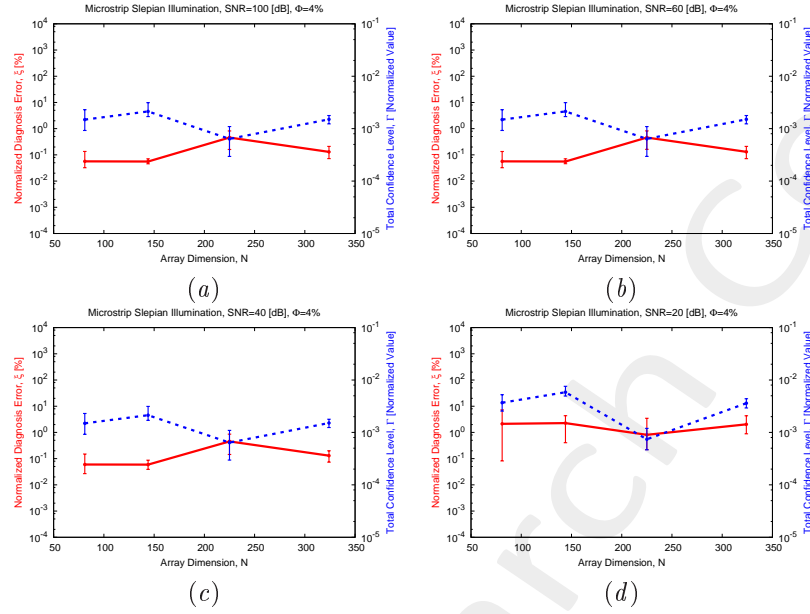


Figure 19: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 4\%$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the array size (N), for (a) SNR = 100 [dB], (b) SNR = 60 [dB], (c) SNR = 40 [dB], and (d) SNR = 20 [dB].

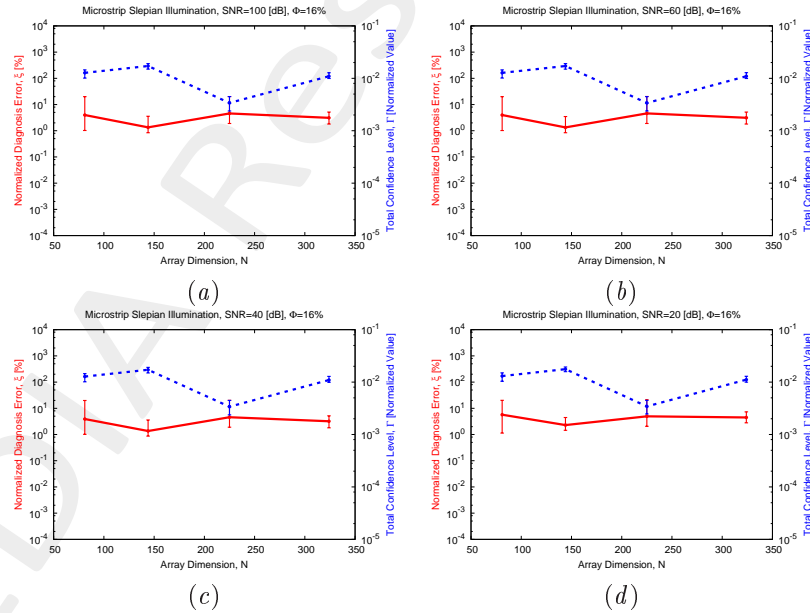


Figure 20: *Microstrip Patches Array* ($N = 324$, $d_x = d_y = 0.5 [\lambda]$, $\Phi = 16\%$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the array size (N), for (a) SNR = 100 [dB], (b) SNR = 60 [dB], (c) SNR = 40 [dB], and (d) SNR = 20 [dB].

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