

Diagnosis of Planar Phased Arrays Through a Probabilistic Compressive Sensing Approach

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Abstract

This work deals with the detection of faulty elements in planar phased antenna arrays starting from far-field pattern measurements. Owing to the intrinsically *sparse* nature of the problem unknowns at hand, the diagnosis problem is formulated as a probabilistic Compressive Sensing (*CS*) one and it is effectively and efficiently solved through a customized Bayesian *CS* (*BCS*) solution approach. Some representative synthetic benchmarks are shown in order to verify the potentialities as well as the current limitations of the proposed *BCS*-based diagnosis tool, as well as to assess its flexibility in dealing with arbitrary excitation taperings of the *AUT*.

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1 Numerical Validation

1.1 Bayliss Array, $N = 316$, Isotropic Sources

Parameters

- Gold Array
 - Total number of elements: $N = 316$;
 - Type of elements: isotropic/ideal ¹;
 - Spacing along x and y : $d_x = d_y = 0.5 [\lambda]$;
 - Excitation tapering: Bayliss;
 - * Radius: $R = 5 [\lambda]$;
 - * Transition index: $t = 3$;
 - * Peak sidelobe level: $PSL = 25 [\text{dB}]$;

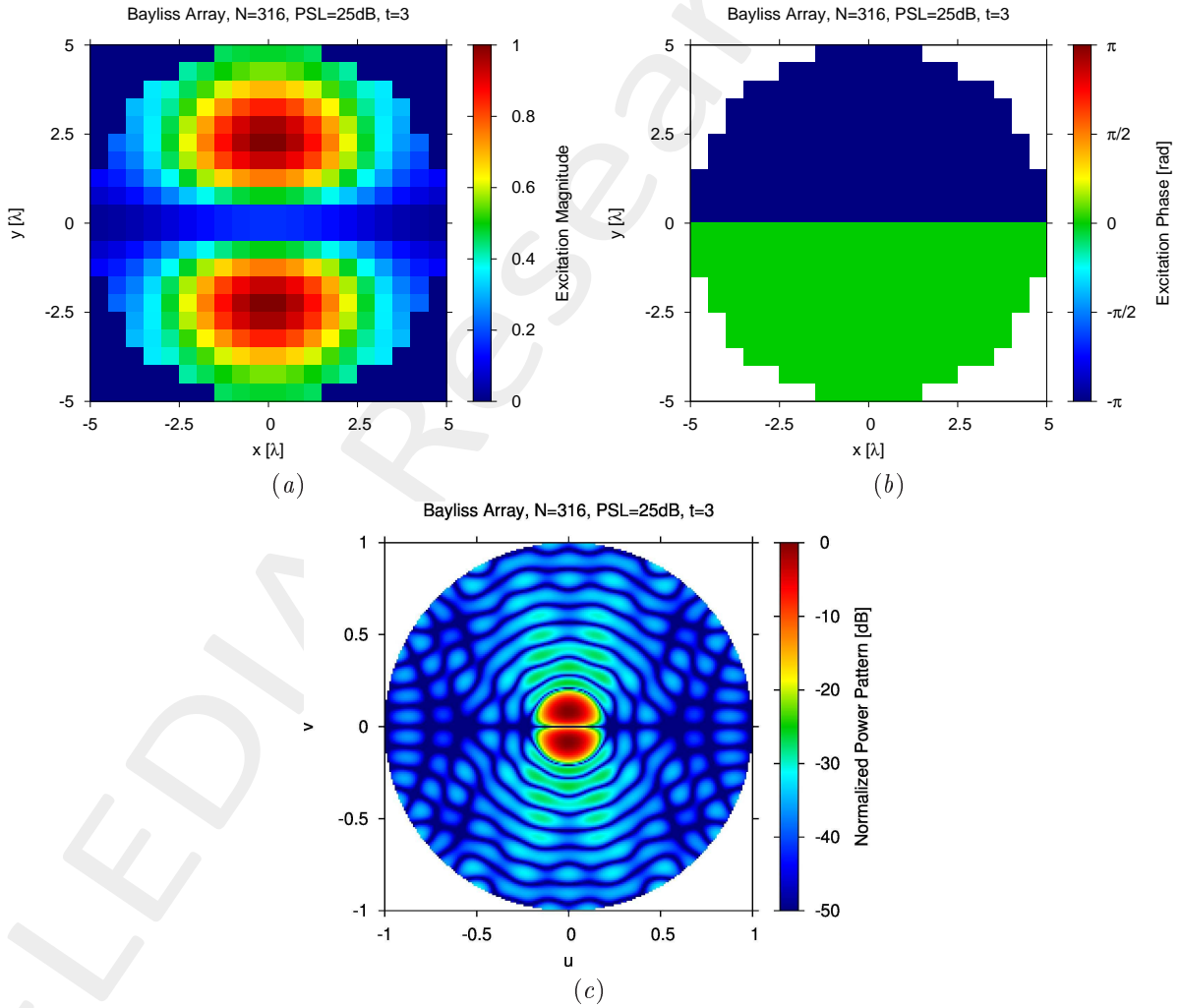


Figure 1: (a) magnitude and (b) phase of the array excitations; (c) normalized power pattern.

¹In order to model *isotropic* radiators, let us assume that the embedded elements patterns are equal to $F_\theta^{(n)}(u, v) = 1$ and $F_\varphi^{(n)}(u, v) = 0$, for $n = 1, \dots, N$.

- Failed Array
 - Failure factor: $\kappa = 0$ (total failures);
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
3	1%
6	2%
13	4%
25	8%
51	16%

Table 1: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points in the visible range: $K = 317$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

Results

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 3$) - Best and Worst *BCS* Reconstructions

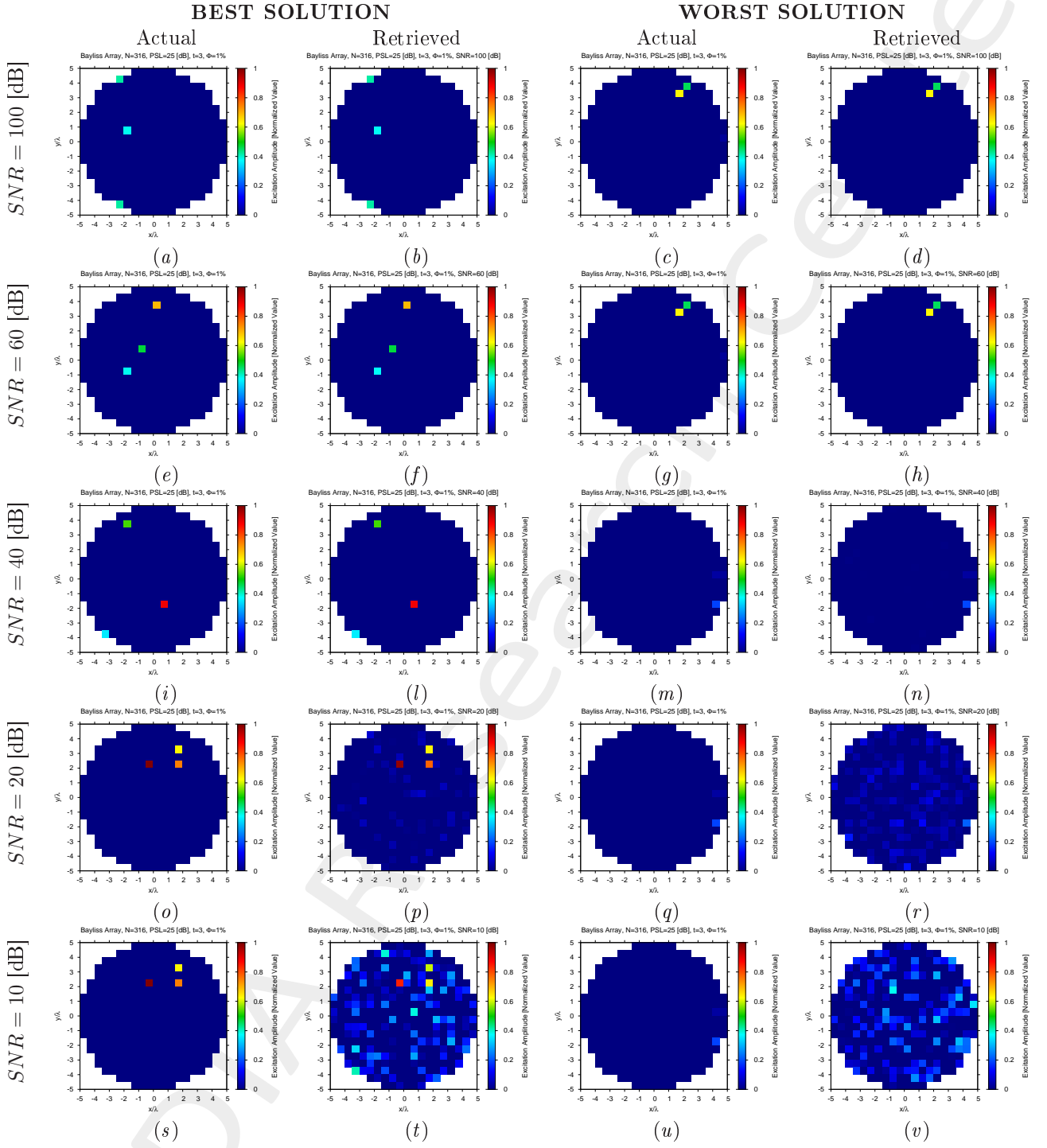


Figure 2: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$, $\Phi = 1\%$) - Best and worst reconstructions by *BCS* under several SNR values.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 6$) - Best and Worst *BCS* Reconstructions

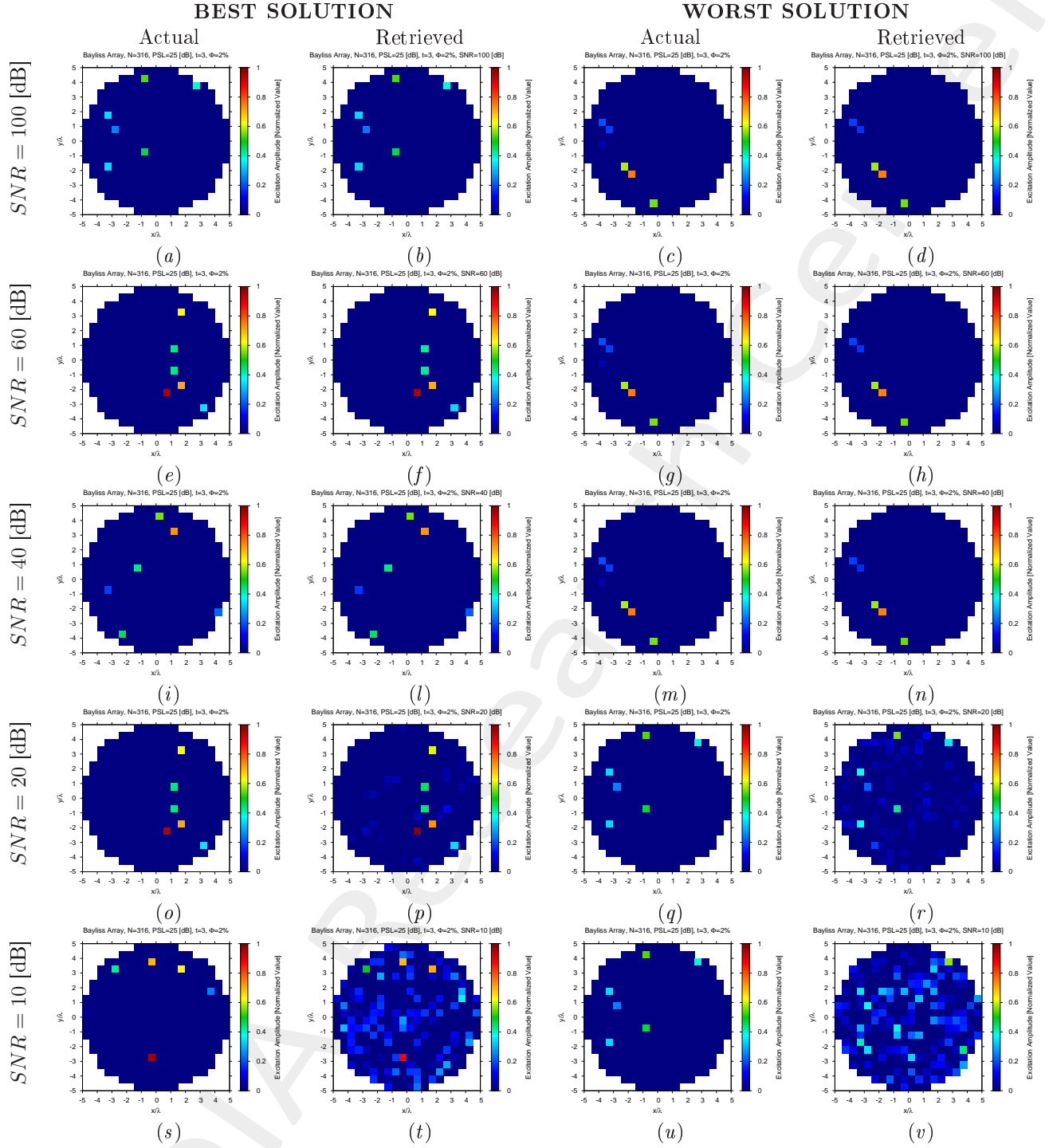


Figure 3: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$, $\Phi = 2\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 13$) - Best and Worst *BCS* Reconstructions

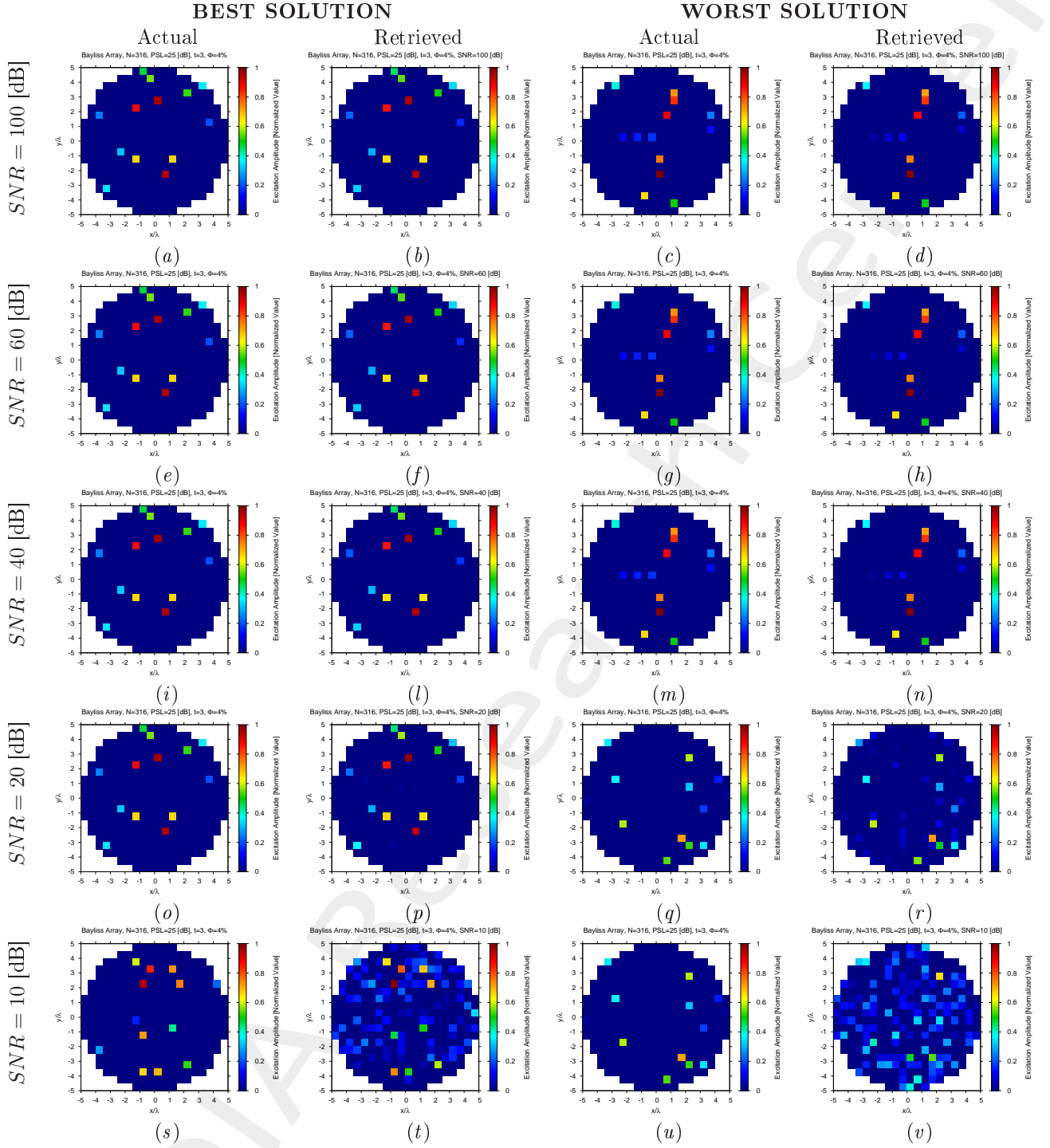


Figure 4: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$, $\Phi = 4\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$$\Phi = \frac{N_f}{N} = 8\% \quad (N_f = 25) \text{ - Best and Worst } BCS \text{ Reconstructions}$$

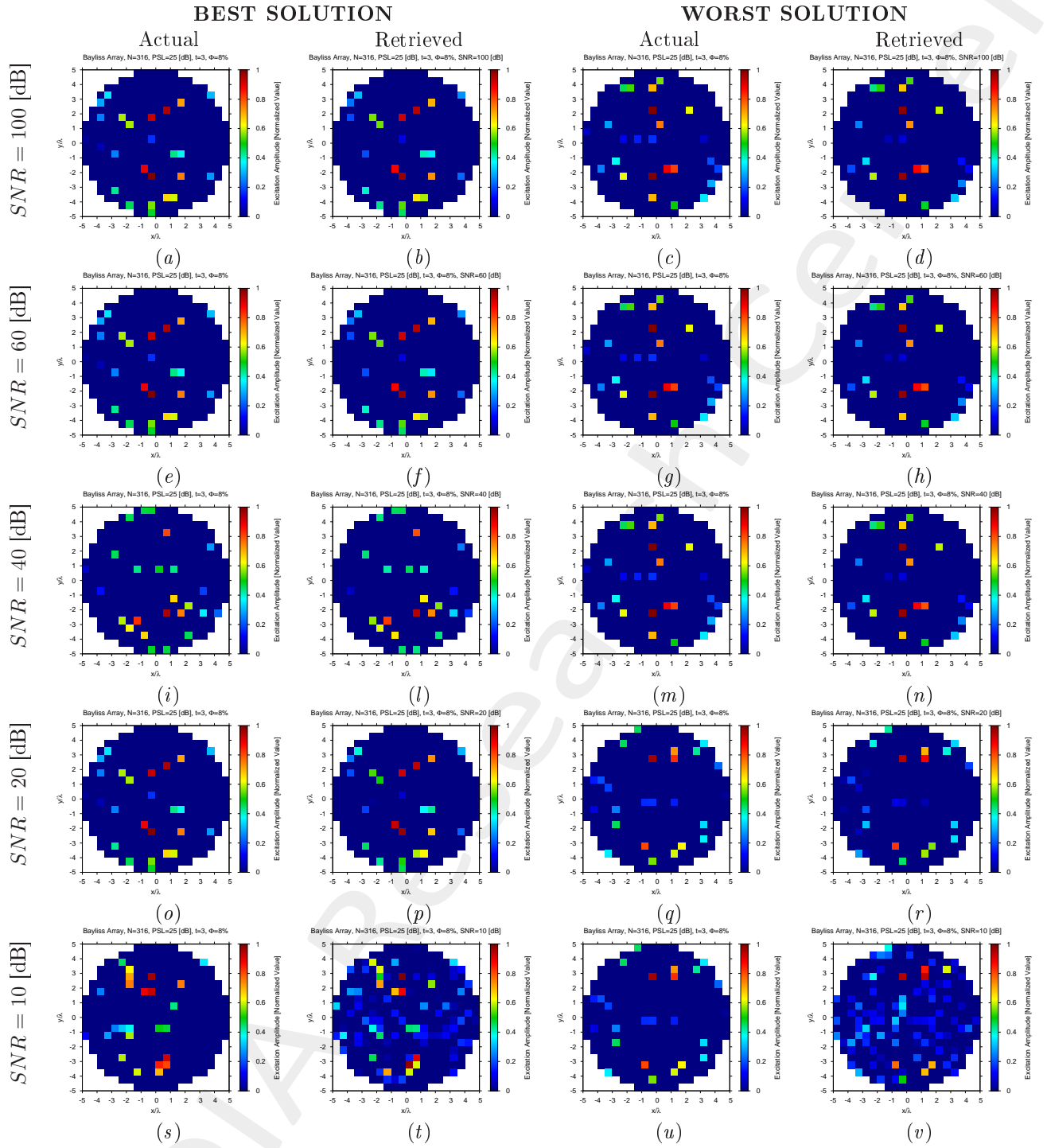


Figure 5: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$, $\Phi = 8\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$$\Phi = \frac{N_f}{N} = 16\% \quad (N_f = 51) - \text{Best and Worst } BCS \text{ Reconstructions}$$

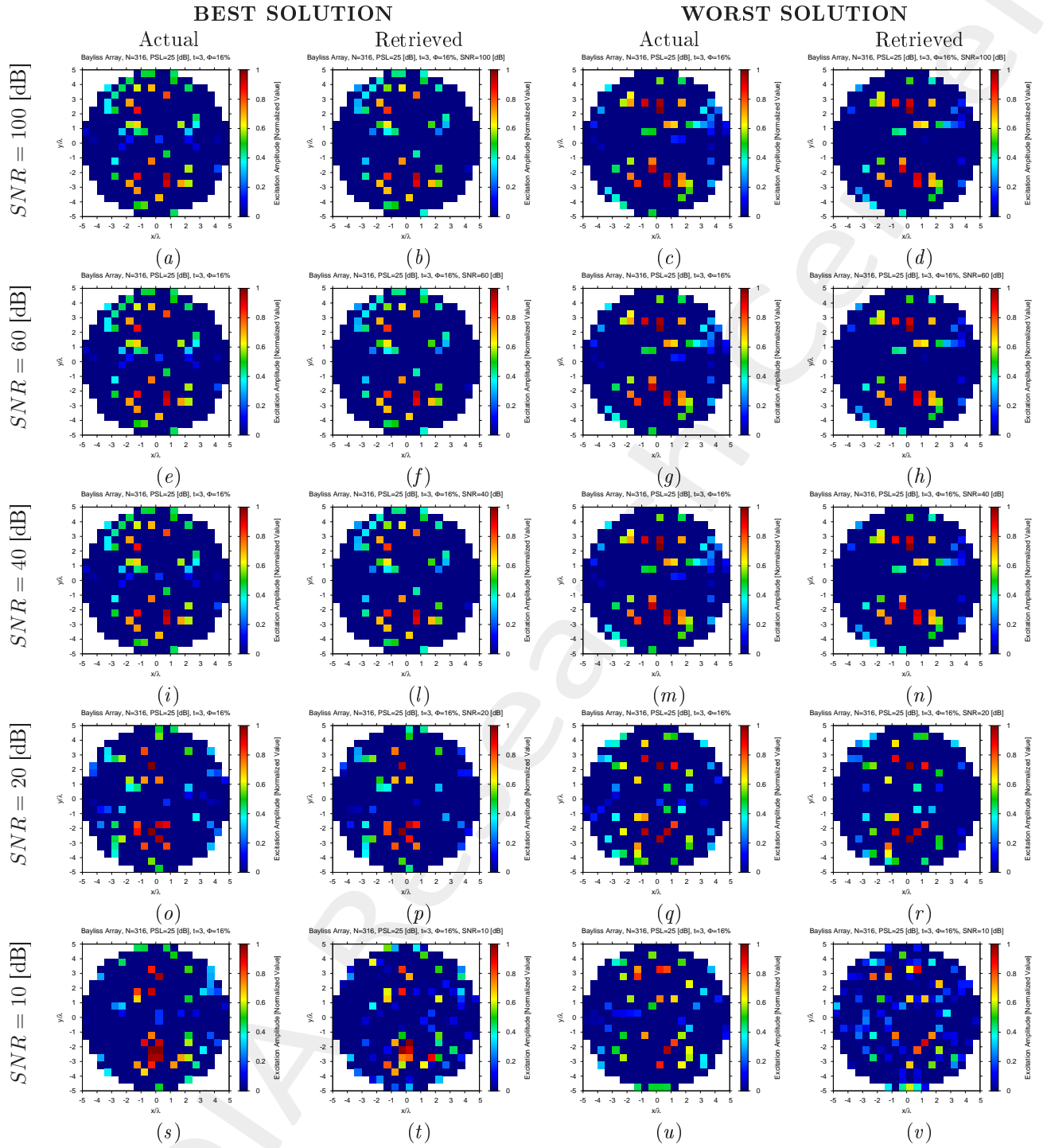


Figure 6: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$, $\Phi = 16\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

Diagnosis Error and Confidence Level

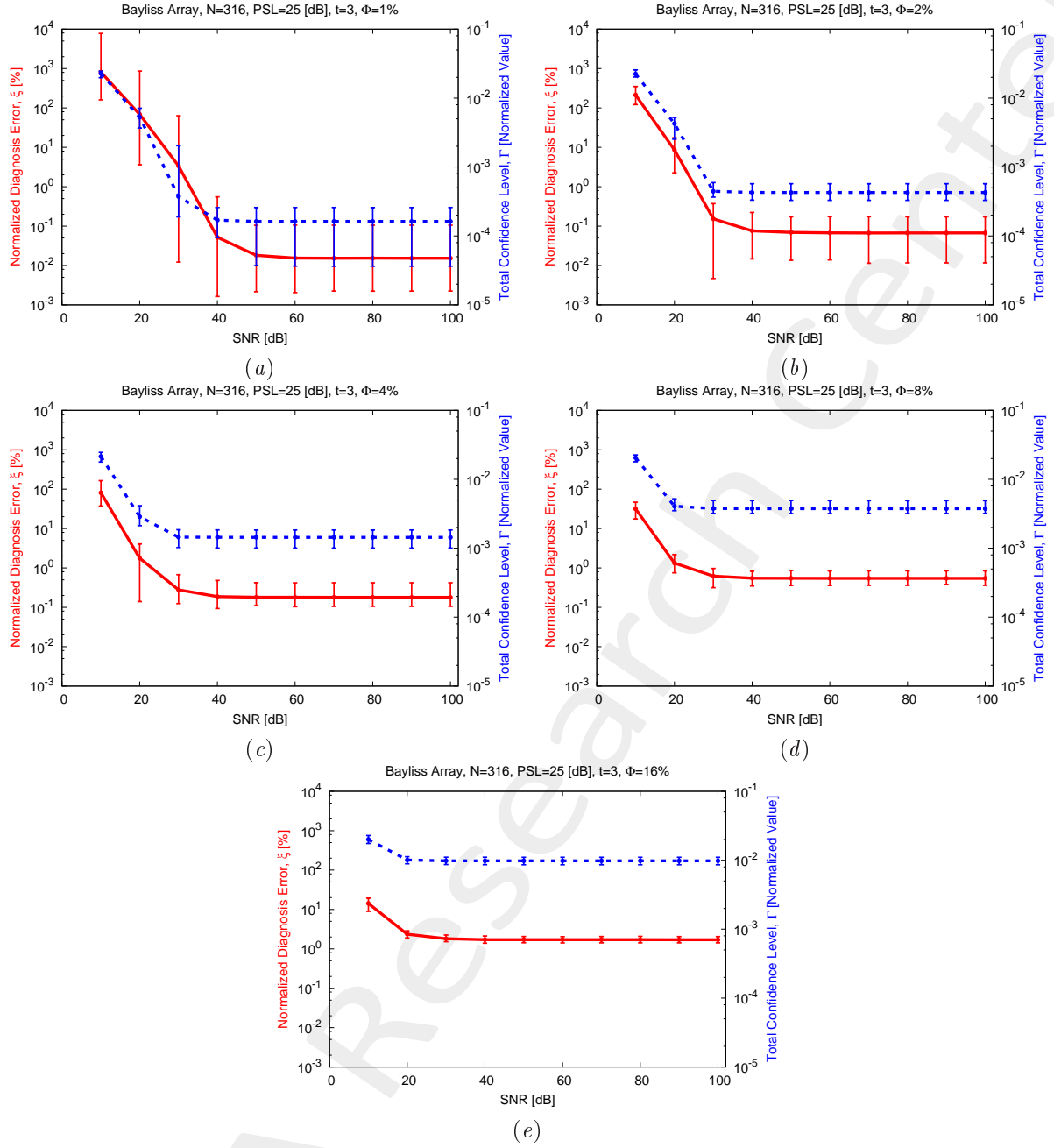


Figure 7: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the SNR , for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

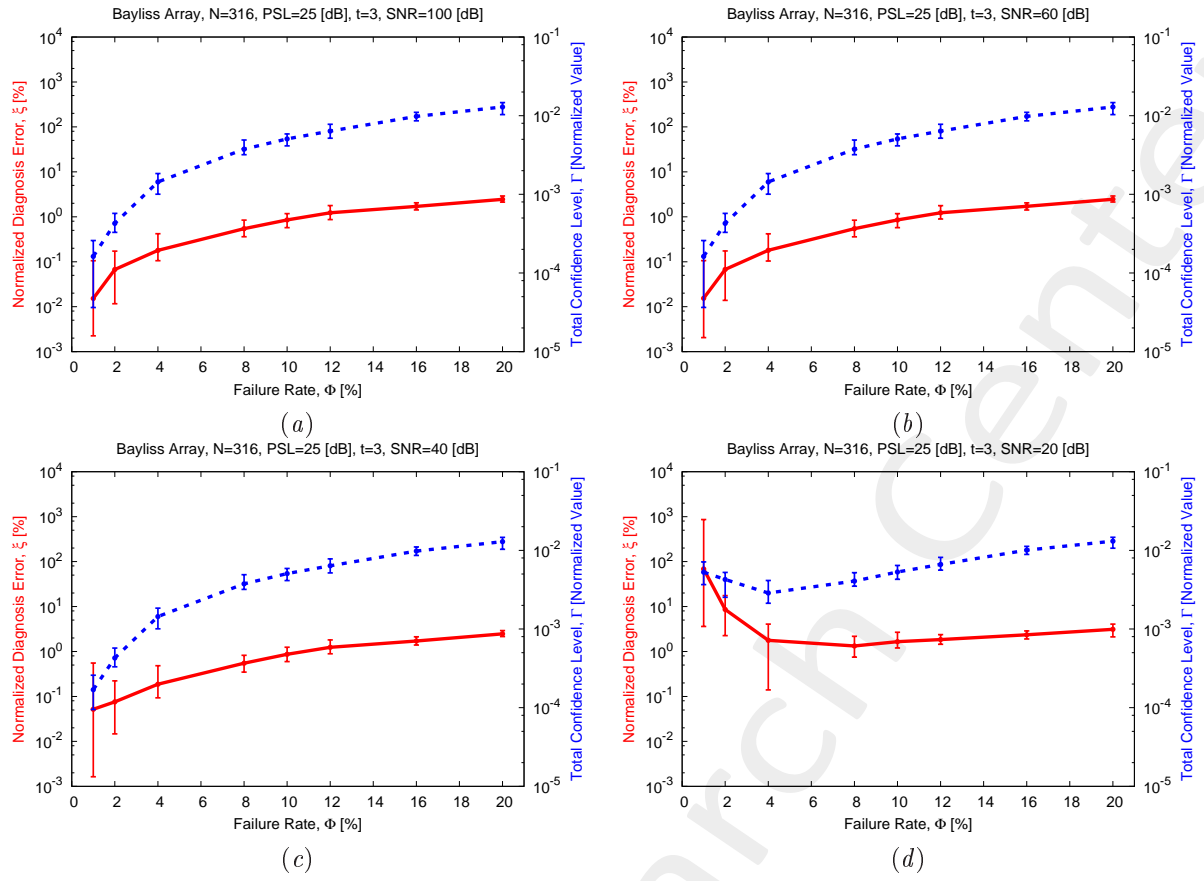


Figure 8: Bayliss Array ($N = 316$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

1.2 Slepian Array, $N = 400$, Isotropic Sources

Parameters

- Gold Array

- Total number of elements: $N = 400$;
- Type of elements: isotropic/ideal ²
- Spacing along x and y : $d_x = d_y = 0.5 [\lambda]$;
- Excitation tapering: Slepian;

* Angular region at the receiver: $\Psi = \{(u, v) : -u_0 \leq u \leq u_0, -v_0 \leq v \leq v_0\}$, with $u_0 = v_0 = 0.1$.

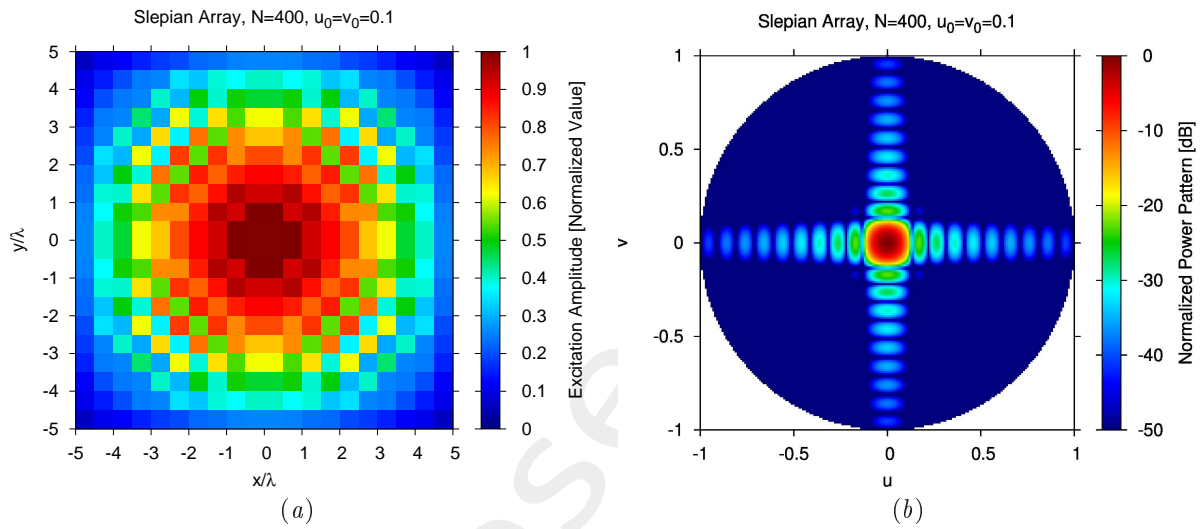


Figure 9: (a) Array excitations and (b) normalized power pattern of the gold array.

- Failed Array

- Failure factor: $\kappa = 0$ (total failures);
- Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
4	1%
8	2%
16	4%
32	8%
64	16%

Table 2: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

- Measurement set-up

²In order to model *isotropic* radiators, let us assume that the embedded elements patterns are equal to $F_\theta^{(n)}(u, v) = 1$ and $F_\varphi^{(n)}(u, v) = 0$, for $n = 1, \dots, N$.

- Type of sampling: uniform sampling in the (u, v) plane;
- Number of points in the visible range: $K = 408$;
- Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 4$) - Best and Worst *BCS* Reconstructions

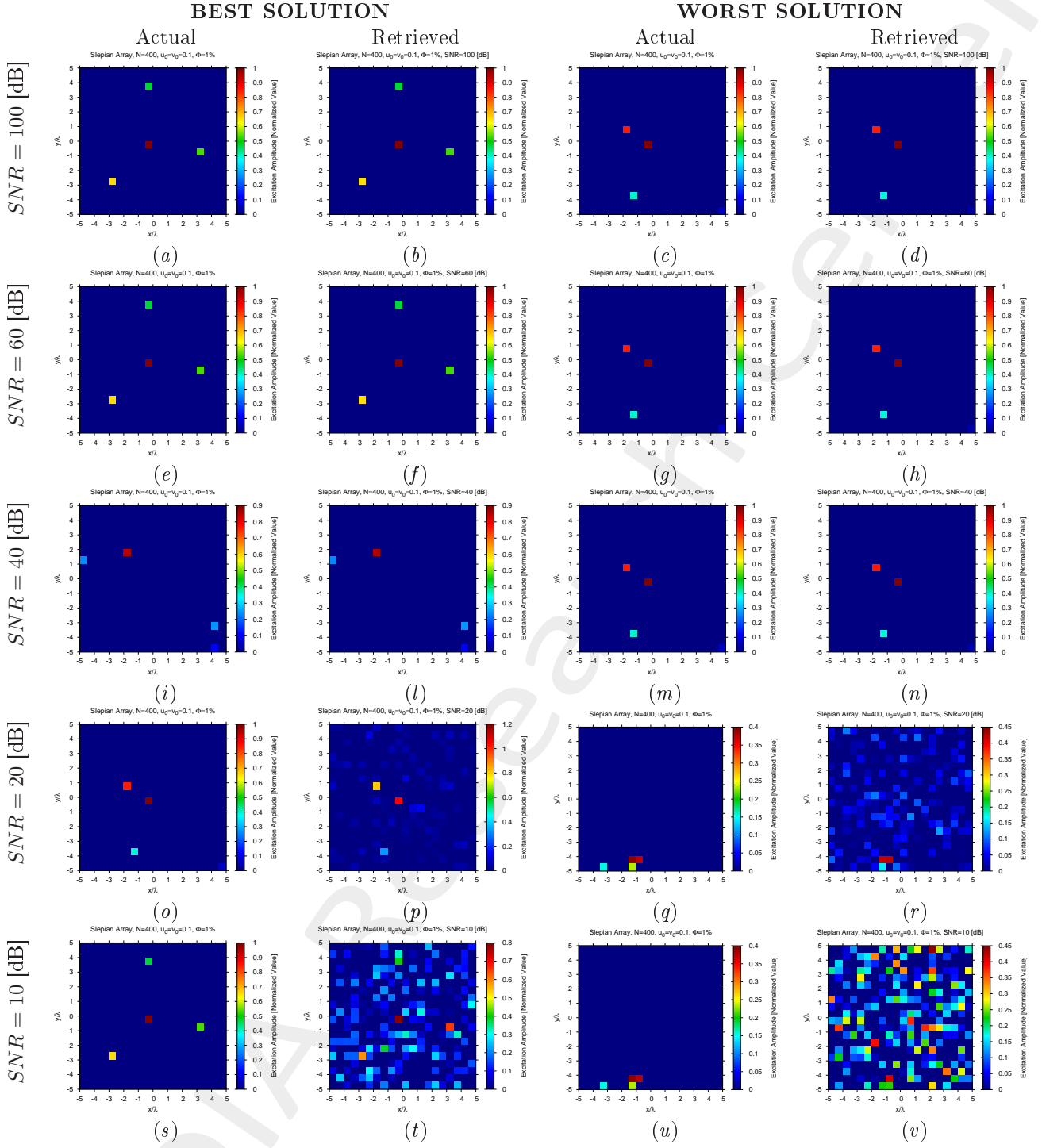


Figure 10: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$, $\Phi = 1\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 8$) - Best and Worst *BCS* Reconstructions

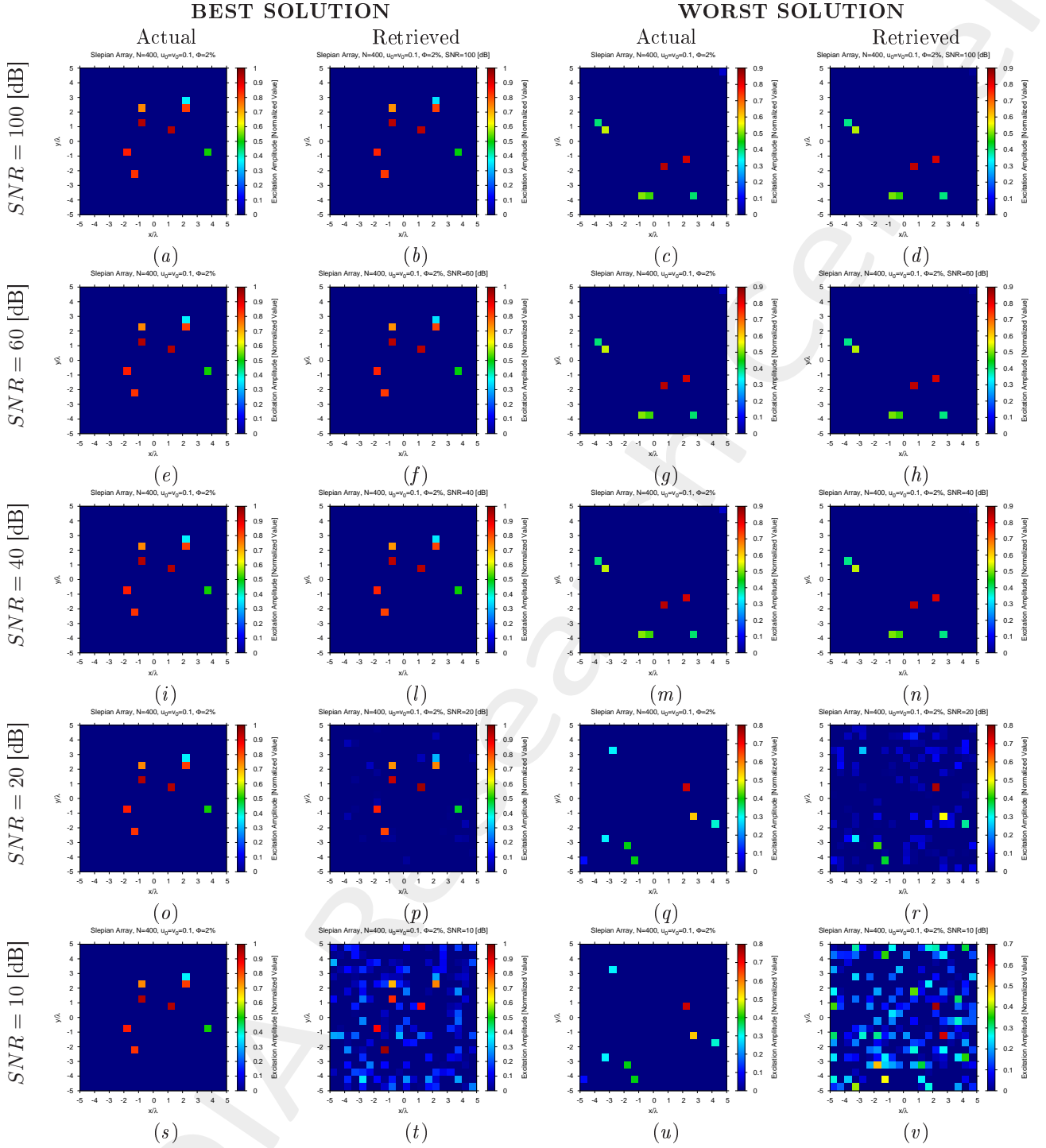


Figure 11: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$, $\Phi = 2\%$) - Best and worst reconstructions by *BCS* under several SNR values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 16$) - Best and Worst *BCS* Reconstructions

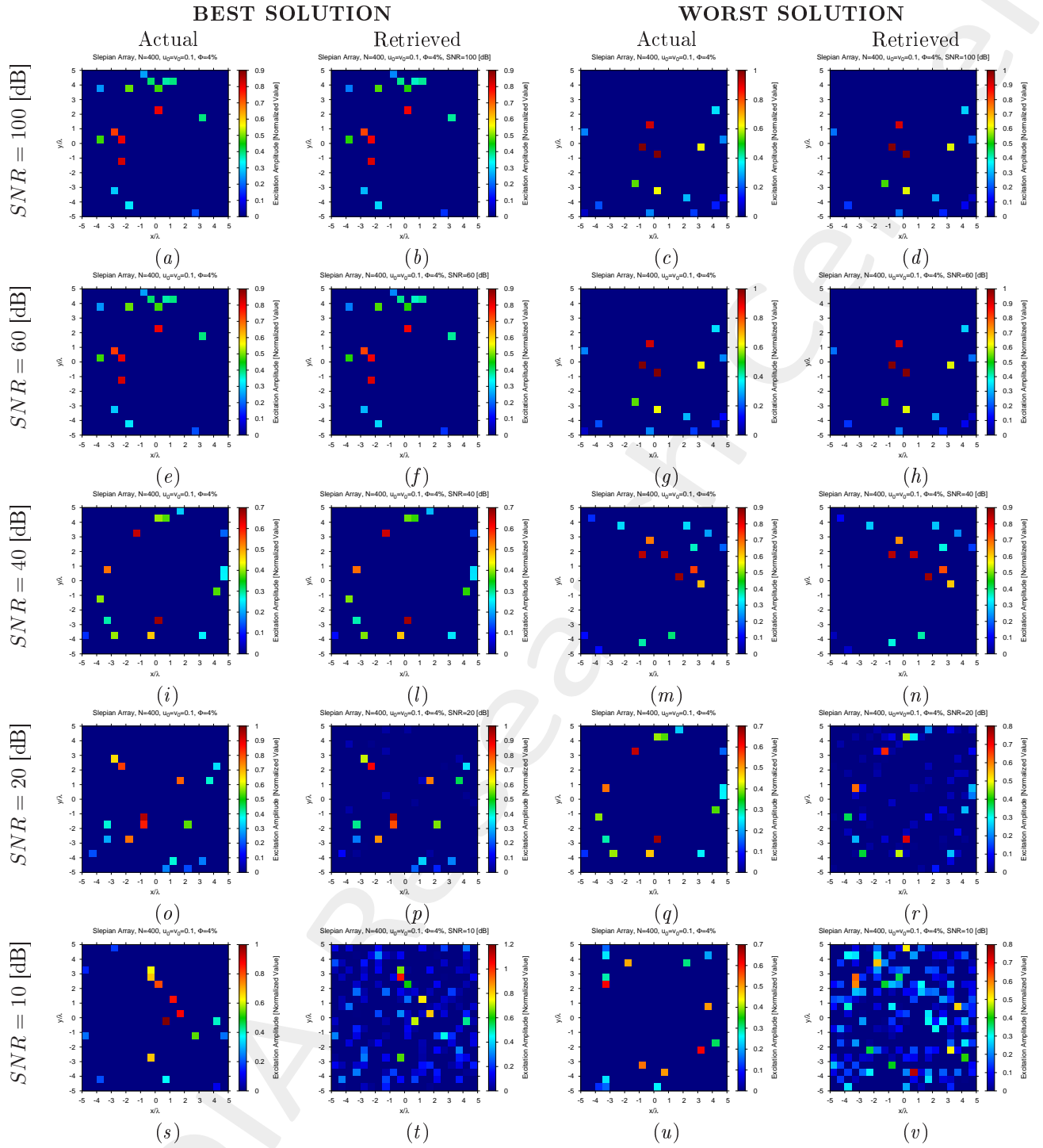


Figure 12: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$, $\Phi = 4\%$) - Best and worst reconstructions by *BCS* under several SNR values.

$\Phi = \frac{N_f}{N} = 8\%$ ($N_f = 32$) - Best and Worst *BCS* Reconstructions

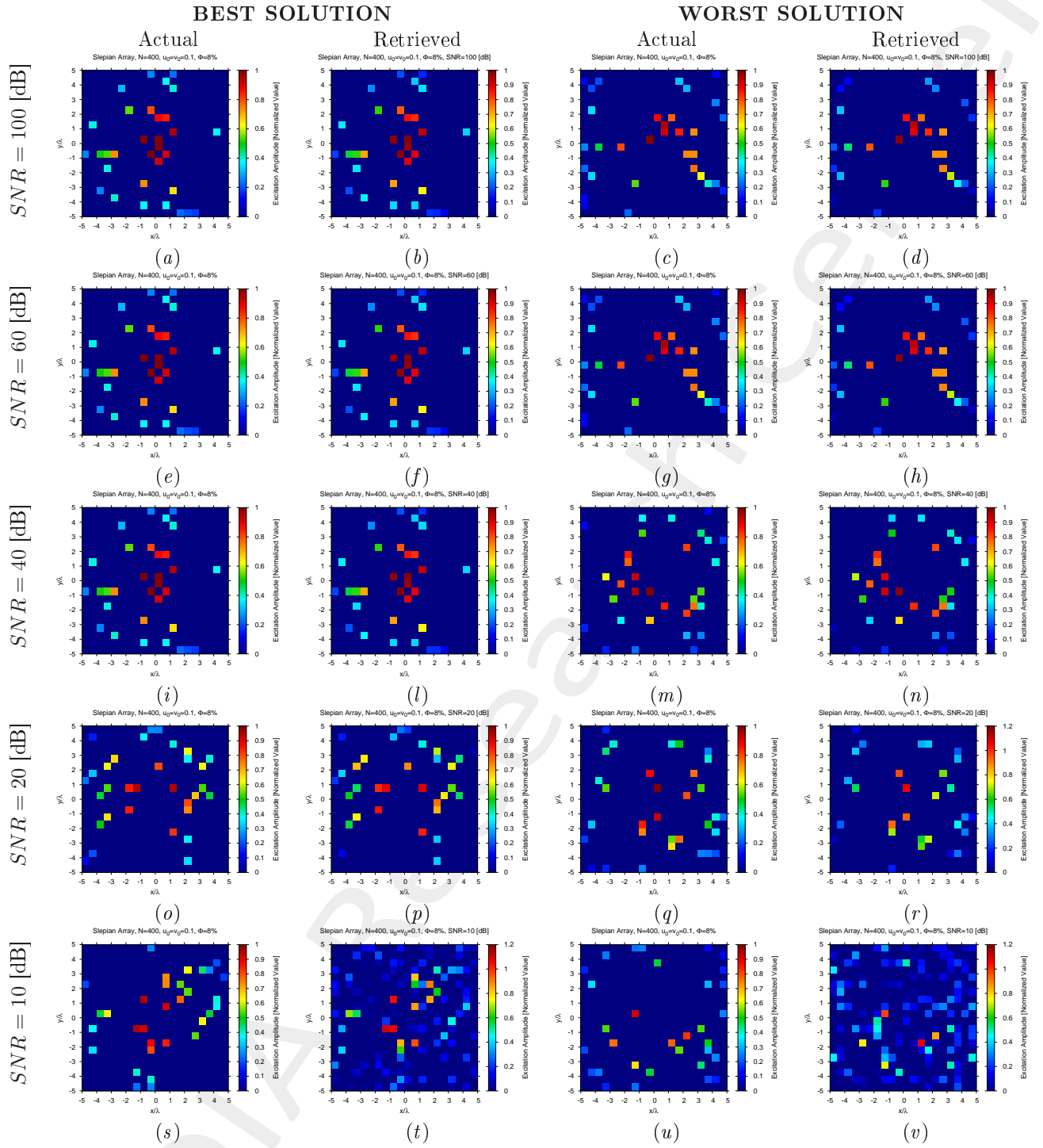


Figure 13: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$, $\Phi = 8\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 16\%$ ($N_f = 64$) - Best and Worst *BCS* Reconstructions

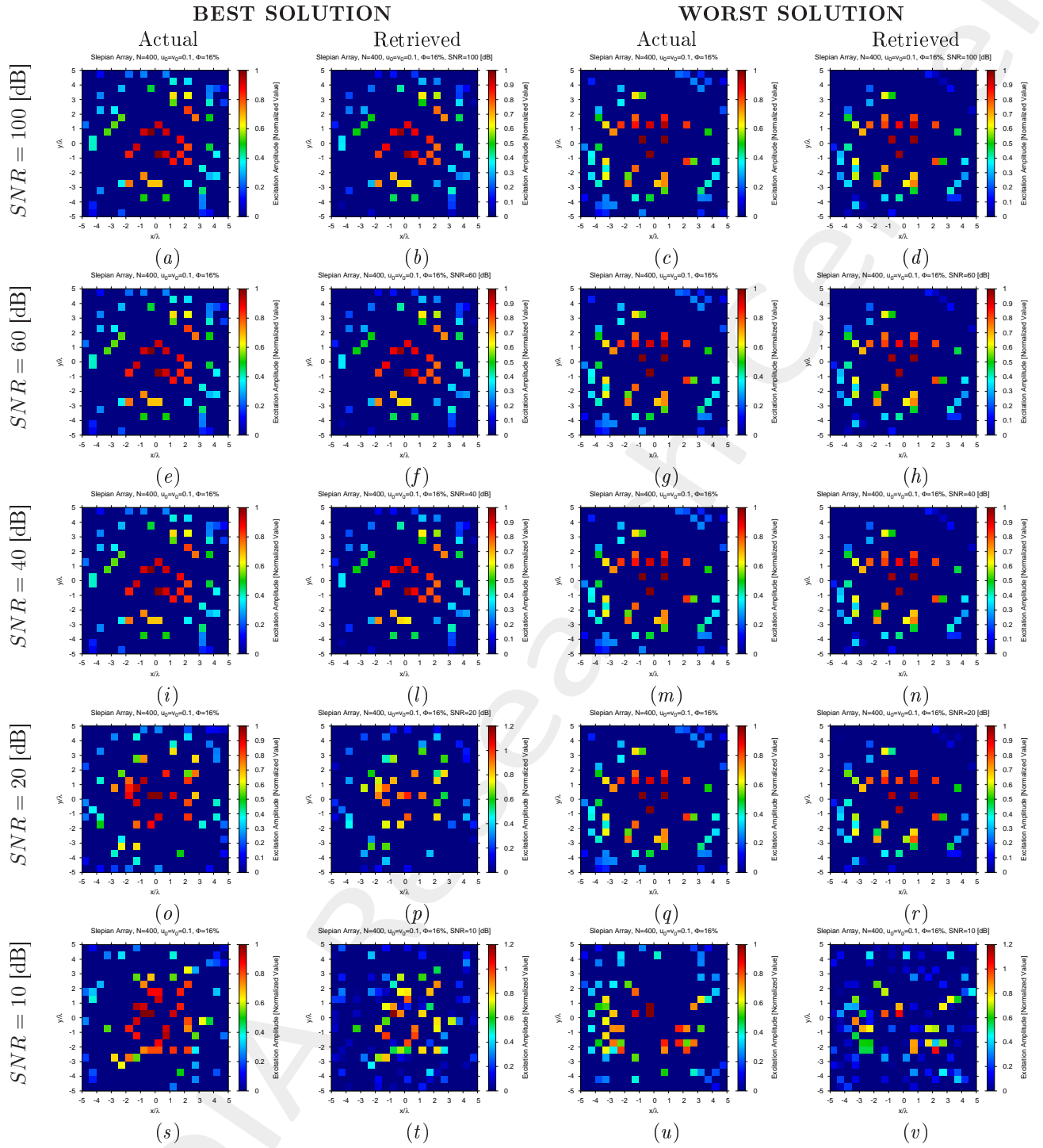


Figure 14: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$, $\Phi = 16\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

Diagnosis Error and Confidence Level

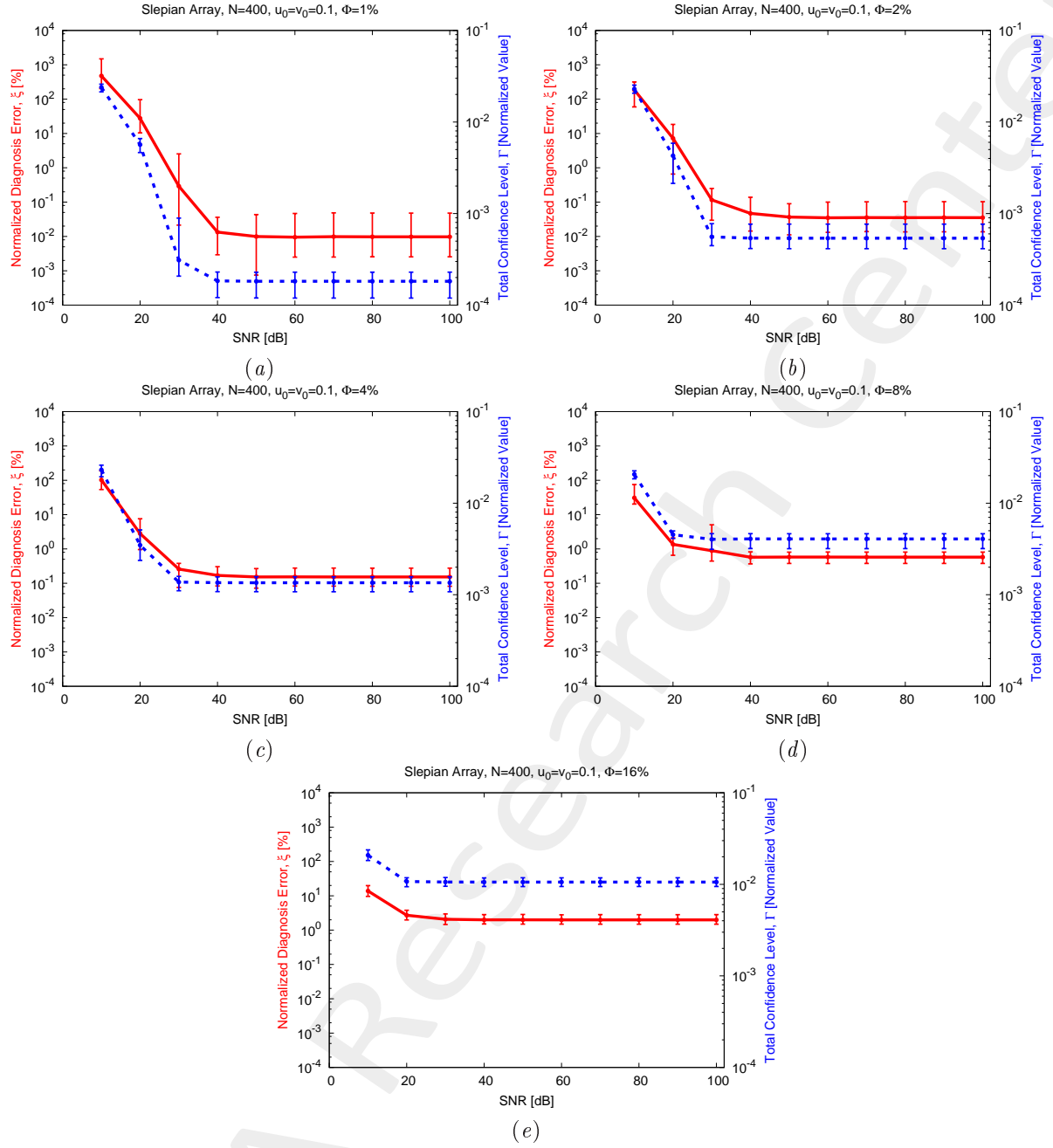


Figure 15: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the SNR, for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, (e) $\Phi = 16\%$.

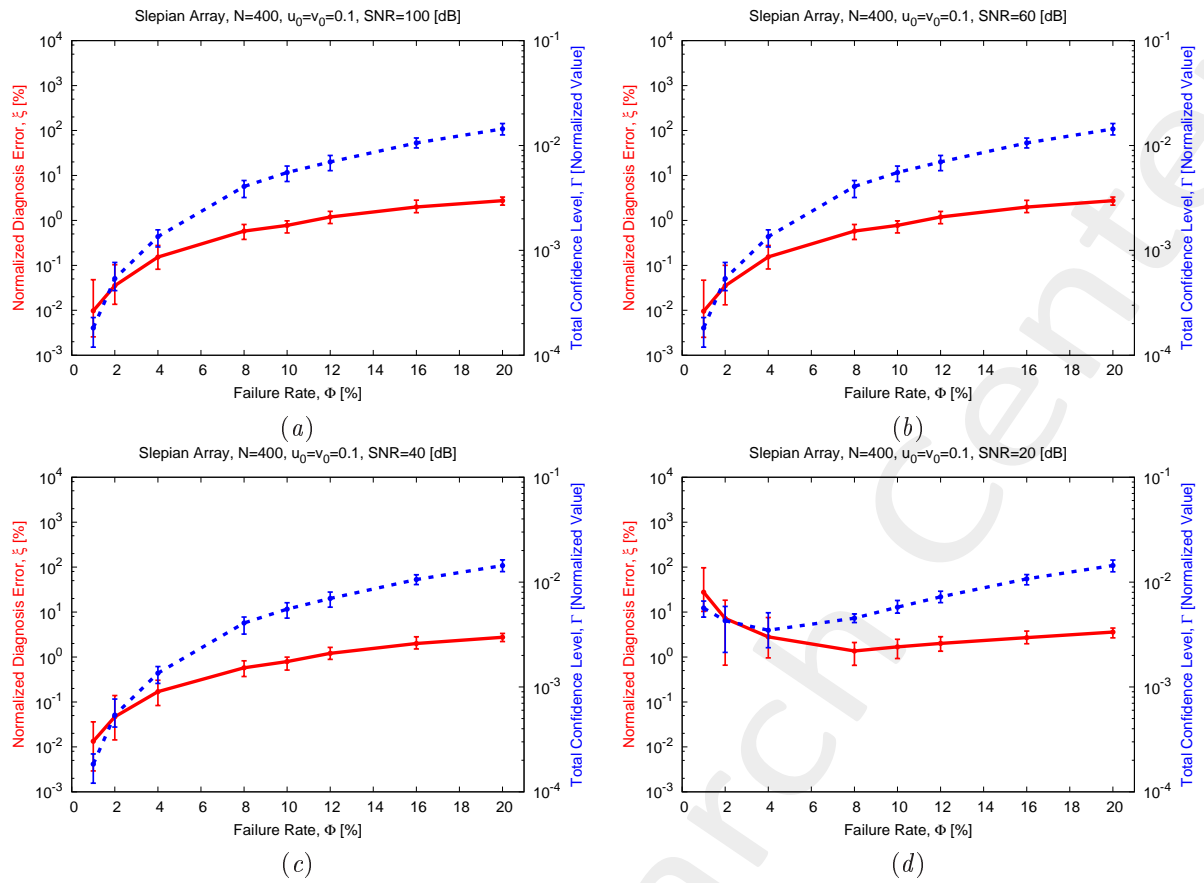


Figure 16: Slepian Array ($N = 400$, $u_0 = v_0 = 0.1$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

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