ADS-Based Arrays for Radioastronomy Applications

G. Oliveri, F. Caramanica, A. Massa

Abstract

The exploitation of low correlation sequences called Almost Difference Sets (ADSs) is considered for the design of correlator arrays for radio astronomy applications. More specifically, an hybrid ADS-GA design method is presented and applied to the synthesis of open-ended "Y" and "Cross" array configurations.

MATHEMATICAL FORMULATION

Quantities related to the radioastronomy array

- Number of total array elements: N
- Array element location: $(x_i, y_i), i = 0, ..., N 1$
- Baselines location: $\mathbf{b}_k = (x_i, y_i) (x_j, y_j), i \neq j$
- Number of baselines: B
- Number of gridded baselines: B^G
- Earth rotation duration: ${\cal H}$
- Discretization of earth rotation: Δh
- Number of baselines after earth rotation: B_R
- Number of gridded baselines after earth rotation: B_R^G
- Gaussian tapering: T [dB]

Quantities related to the GA

- \bullet Population size: P
- Iteration number: I
- Crossover probability: p_{ξ}
- Mutation probability: p_{μ}
- Fitness definition: $F = \alpha \times \frac{1}{PSL} + \beta \times \frac{1}{N} + \gamma \times \frac{1}{B} + \delta \times \frac{1}{B_R^G}$

GOAL: minimize the PSL of a triangular shaped array by means of ADSs chosen by means of a GA. The same ADS is employed in the three arms, with different shifts.

- Number of array arms: A
- Arm length: $L_i, i = 0, .., A 1$
- Number of array elements for each arm: N_i , i = 0, .., A 1 $(N = \sum_{i=0}^{A-1} N_i)$
- Array rotation with respect to north-south: ρ [deg]

Test Case Description

Geometry:

- Triangular array: A = 3
- $L_i = 21 \text{ [Km]} \forall i \in 0, .., A 1$
- Element number: $N_i = 9 \ \forall i \in 0, .., A 1$ (the same ADS is employed in the three arms)
- Unconstrained last elements (lattice spacing: $d_i = \frac{L_i}{N_i 1}$)
- $\rho = 0$ [deg]
- $T = -15 \, [dB]$

Geographical information:

- Array rotation duration: H = 8 [h]
- Sampling step: $\Delta h = 5$ [min]
- Latitude: 34 [deg]
- Elevation: 0 [deg]
- Declination: 34 [deg]

Numerical simulation parameters:

- Grid discretization: $G_X \times G_Y = 128 \times 128$
- Grid dimension: $D_X \times D_Y = 50000 \times 50000 \ [\lambda^2]$
- FFT dimension: $F_L \times F_M = 512 \times 512$

- P = 20
- I = 400
- $p_{\xi} = 0.9$
- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 1.

• The PSL behaviour is far from that of [2] (around than 3 dB worse)

Figure

N





30

20

10

y [km]



ADS-Based array, N=27

Element location •

30





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- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 3.

Figure

4

Observations:

ADS-Based array, N=27

21 [km]

0

ADS-Based array, N=27

-500 -400 -300 -200 -100 0 100 200 300 400 500

(c)

u [λ×1000] Rotated baseline function W_R(u,v)

x [km] (a)

Element location •

10

20

30

30

20

10

-10

-20

-30

-30

500

400

300

200

100

0

-100

-200 -300

-400

v [\x1000]

-20

-10

y [km] 0







(d)

Optimal geometry, autocorrelation, rotated autocorrelation and pattern

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- Unconstrained last elements (lattice spacing: $d_i = \frac{L_i}{N_i 1}$)
- $\rho = 5$ [deg]
- $T = -15 \, [dB]$

Geographical information:

- Array rotation duration: H = 8 [h]
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- P = 20
- I = 400
- $p_{\xi} = 0.9$
- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 5.

Figure

6

Observations:

ADS-Based array, N=27

2

Ikm

0

x [km] (a)

ADS-Based array, N=27

-500 -400 -300 -200 -100 0 100 200 300 400 500

(c)

u [λ×1000] Rotated baseline function W_R(u,v)

10

20

30

Element location •

30

20

10

0

-10

-20

-30

-30

500

400

300

200

100

0

-100

-200 -300

-400

v [\x1000]

-20

-10

y [km]







Optimal geometry, autocorrelation, rotated autocorrelation and pattern

GOAL: minimize the PSL of a triangular shaped array by means of ADSs chosen by means of a GA. The same ADS is employed in the three arms, with different shifts.

- Number of array arms: A
- Arm length: $L_i, i = 0, .., A 1$
- Number of array elements for each arm: N_i , i = 0, .., A 1 $(N = \sum_{i=0}^{A-1} N_i)$
- Array rotation with respect to north-south: ρ [deg]

Test Case Description

Geometry:

- Triangular array: A = 3
- $L_i = 21 \text{ [Km]} \forall i \in 0, .., A 1$
- Element number: $N_i = 9 \ \forall i \in 0, .., A 1$ (the same ADS is employed in the three arms)
- Constrained last element of each arm (arm length is constant, spacing is not constant)
- $\rho = 5$ [deg]
- $T = -15 \, [dB]$

Geographical information:

- Array rotation duration: H = 8 [h]
- Sampling step: $\Delta h = 5$ [min]
- Latitude: 34 [deg]
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- FFT dimension: $F_L \times F_M = 512 \times 512$

- P = 20
- I = 400
- $p_{\xi} = 0.9$
- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 7.

• The PSL behaviour is far from that of [2] (around than 2.5 dB worse)

Figure

Ø

Observations:

ADS-Based array, N=27

21 [km]

0

x [km] (a)

ADS-Based array, N=27

-500 -400 -300 -200 -100 0 100 200 300 400 500

(c)

u [λ×1000] Rotated baseline function W_R(u,v)

Element location •

10

20

30

30

20

10

0

-10

-20

-30

-30

500

400

300

200

100

0

-100

-200 -300

-400

v [\x1000]

-20

-10

y [km]







Optimal geometry, autocorrelation, rotated autocorrelation and pattern

- 1-

0

-5

-10 function W(u,v)

-15

-20

-25 -25-Baseline f

-35

-40

14

RESUME: PSL MINIMIZATION, SAME ADS for all arms, DIF-FERENT SHIFTS

PSL behaviour with respect to iteration number for optimal arrays



Figure 9.

Overall observations:

- The reported results show that there is not a significant dependency of the obtained PSL from the considered rotation angle (ρ) or the constrained/unconstrained geometry, since all the optimal solutions provide a PSL which is between -17.65 dB and -17.4 dB.
- However, it turns out that constrained and rotated geometries provide a slightly better PSL behaviour.
- It has to be remarked that, in all cases, the obtained PSL is far from that of [2]

GOAL: minimize the PSL of a triangular shaped array by means of ADSs chosen by means of a GA. **Different** ADSs are employed in the three arms, with different shifts.

- Number of array arms: A
- Arm length: $L_i, i = 0, .., A 1$
- Number of array elements for each arm: N_i , i = 0, .., A 1 $(N = \sum_{i=0}^{A-1} N_i)$
- Array rotation with respect to north-south: ρ [deg]

Test Case Description

Geometry:

- Triangular array: A = 3
- $L_i = 21 \, [\text{Km}] \, \forall i \in 0, .., A 1$
- Element number: $N_i \leq 9 \ \forall i \in 0, .., A-1$
- Unconstrained last elements on each arm (lattice spacing: $d_i = \frac{L_i}{N_i 1}, i \in 0, ..., A 1$)
- $\rho = 0$ [deg]
- $T = -15 \, [dB]$

Geographical information:

- Array rotation duration: H = 8 [h]
- Sampling step: $\Delta h = 5$ [min]
- Latitude: 34 [deg]
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Numerical simulation parameters:

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- Grid dimension: $D_X \times D_Y = 50000 \times 50000 \ [\lambda^2]$
- FFT dimension: $F_L \times F_M = 512 \times 512$

- P = 20
- I = 400
- $p_{\xi} = 0.9$
- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 10.

• The PSL behaviour is far from that of [2]



Figure 11.







GOAL: minimize the PSL of a triangular shaped array by means of ADSs chosen by means of a GA. **Different** ADSs are employed in the three arms, with different shifts.

- Number of array arms: A
- Arm length: $L_i, i = 0, .., A 1$
- Number of array elements for each arm: N_i , i = 0, .., A 1 $(N = \sum_{i=0}^{A-1} N_i)$
- Array rotation with respect to north-south: ρ [deg]

Test Case Description

Geometry:

- Triangular array: A = 3
- $L_i = 21 \text{ [Km]} \forall i \in 0, .., A 1$
- Element number: $N_i \leq 9 \ \forall i \in 0, .., A-1$
- Constrained last elements on each arm (arm length is constant, spacing is not constant)
- $\rho = 0$ [deg]
- $T = -15 \, [dB]$

Geographical information:

- Array rotation duration: H = 8 [h]
- Sampling step: $\Delta h = 5$ [min]
- Latitude: 34 [deg]
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- FFT dimension: $F_L \times F_M = 512 \times 512$

- P = 20
- I = 400
- $p_{\xi} = 0.9$
- $p_{\mu} = 0.01$
- $\alpha = 1, \ \beta = \gamma = \delta = 0$





Figure 12.



Observations:

ADS-Based array, N≤27

21 [km]

0

ADS-Based array, N≤27

-500 -400 -300 -200 -100 0 100 200 300 400 500

(c)

u [λ×1000] Rotated baseline function W_R(u,v)

x [km] (a)

Element location •

10

20

30

30

20

10

0

-10

-20

-30

-30

500

400

300

200

100

-400

v [\x1000] 0 -100 -200 -300 -20

-10

y [km]

Figure 13.







RESUME: PSL MINIMIZATION, DIFFERENT ADS for all arms, DIFFERENT SHIFTS

PSL behaviour with respect to iteration number for optimal arrays



Figure 14.

Overall observations:

- The reported results show that there is not a significant dependency of the obtained PSL from the constrained/unconstrained geometry, since the optimal solutions provide a PSL which is very close.
- One can notice that allowing different ADS to be employed results in lower performances in the first steps of the optimization, while essentially the same performances resulting in the previous case (same ADS employed in all arms; the employed ADS correspond to the largest allowed in this case) are actually obtained. This is due to the fact that the PSL minimization selects those arrays with the maximum number of elements. As a consequence, in the last steps the two methods coincide (in both cases, all the arms employs the same ADS, i.e. the largest allowed).
- It has to be remarked that, in all cases, the obtained PSL is far from that of [2]

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